The Tomorrow.io Weather Constellation: Status and Early On-Orbit Results

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Overview





Enabling Accurate Global Precipitation Nowcasts and Improved Medium-Range Weather Forecasts



 IMERG (IR + PMW – PDIR algorithm) has been the standard for Satellite Precip Estimation, but has substantially lower skill than radar (and w/ >3h latency).



Most of the globe does not have radar, and precipitation nowcasting is fundamentally different/less skillful in these regions.

- New satellite observations are essential to improve traditional and ML precipitation nowcasting at global scales.
- Tomorrow.io sounder/radar constellation is expected to fill much of the skill/lead time gap between ground radar- and Geo satellite-based precipitation nowcasts worldwide.
- Global, rapid-revisit microwave sounder and scanning radar observations will have a positive impact on medium-range NWP (Ryan Honeyager's talk)

Meet the Tomorrow.io Satellite Constellation



- Full Global Coverage
- <1 hour average revisit rate
- World's first near real-time precipitation measurements and 3D atmospheric profiles
- Dramatic improvement in real-time weather forecasts, tropical cyclone warnings and flood alerts

Hybrid constellation of 26 small satellites in Low Earth Orbit

- 8 Ka-band radars
- 18 MW radiometers

Timeline:

- Launches began in Q2/23
- Constellation fully operational by EOY 2026

Development & Launch Timeline



The TMS constellation will vastly improve upon the program of record's revisit, latency, and age-of-data:



Age of data (age of most recent observation available in real-time) by latitude for 11 PMW sensors in current GPM constellation (3xATMS, 3xMHS, 3xSSMIS, GMI, AMSR2). Age of data depends on revisit rate and latency. 10th-90th percentiles and mean are shown.

Age of data for the full Tomorrow.io sounder constellation (18 satellites). Mix of SSO and 45-degree inclined orbits. 10th-90th percentiles and mean are shown.



Pathfinder Radar Program Update



Tomorrow.io Radar Pathfinder Program Status

Pathfinder (Tomorrow-R1/R2):

Reflector-based Ka-band PR TR1 Launch: SpaceX Transporter-7, April 14, 2023 TR2 Launch: SpaceX Transporter-8, June 12, 2023



Key Parameters/Objectives:

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- Deploy ARENA[®] SDR in space for the first time
- Acquire precipitation and ocean scattering measurements across 40° swath for operational algorithm development
- Validate radar calibration methods and precipitation retrieval accuracy

Granule File Counts for Constellation-Wide L1C-GEOPROF Observations



40

- 30

Tomorrow.io Radar Pathfinder Highlights



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Tomorrow.io Radar Pathfinder Validation



L1C-GEOPROF

Comparison of Tomorrow-R1 ocean NRCS versus wind speed with KaPR GMF prediction using NWP model winds and accounting for attenuation. Observations are restricted to clear sky and near-nadir incidence. **Overall bias versus KaPR is** -0.4 dB. (b) Same for Tomorrow-R2, with overall bias of <0.1 dB.

L2A-PRECIP

(Left) Scatter density diagram of Tomorrow-R1 and -R2 surface precipitation rate against NOAA MRMS matched to the R1 and R2 beam patterns. Data are from August 2023-March 2024. (Right) Same analysis for the GPM KaPR product during October 2023.





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Microwave Sounder Program Update





Tomorrow.io Microwave Sounder: Bus and Payload





TMS Products



Sample L1B product (simulation from DYAMONDv2 nature

Datasets Catalogs Bookmarks Type Name Long Name TMS01.1B-TB.V00-01.ST20200115-23330... TMS01.1B-TB.V00-01.ST20200115-233300.ET20... Local File Variable "brightness_temperature_ICT" antenna temperature ICT Antenna brightness temperature using internal calibr... Geo2D In file antenna_temperature_ND Antenna brightness temperature using noise diode Geo2D "TMS01.1B-TB.V00-01.ST20200115-233300.ET20200116-002654.CT20240607-165 AUX AUX ____ (1).nc" brightness_temperature_ICT Earth radiometric brightness temperature using inter.. Geo2D brightness temperature ND Earth radiometric brightness temperature us 0 0 0 brightness_temperature_ICT in TMS01.1B-TB.V00-01.ST20200115-233300.ET202 clear fraction Cloud-clear fraction Day UTC day Plot Array 1 encoder angle Scanner encoder angle flagAscDesc Ascending/Descending flag Earth radiometric brightness temperature using internal calibration target flagColdCal Cold Calibration Spot Flag flagDayNight Day/Night flag flagICTCal Internal Calibration Target Spot Flag flagLunarIntrusion Lunar intrusion flag 18 flagManeuver Spacecraft maneuver flag 20 Store flagNDCal Noise Diode Calibration Spot Flag Tas flagNonOcean Non-ocean Flag flagPLOrientation Payload Orientation flag flagSolarIntrusion Lunar intrusion flag Hour UTC hour instrTemp Average instrument temperature Iand fraction Land fraction latitude Latitude: line-of-sight to Earth intersection ··• in the Iongitude Longitude: line-of-sight to Earth intersection Iunar_azimuth_angle Line-of-sight lunar azimuth angle R) lunar_zenith_angle Line-of-sight lunar zenith angle Millisecond UTC millisecond Minute UTC minute Month UTC month MultiMask Combined land/ocean/cloud mask derived S NEDT DS NEDT of cold cal. measurement NEDT_ICT NEDT of internal cal target measurement D S NEDT ND NEDT of hot cal. measurement scAltitude Spacecraft altitude scLatitude Spacecraft latitude scLongitude Spacecraft longitude scPosECEF Spacecraft ECEF position scOuatECEF Spacecraft Body-to-ECEF quaternion scRollAngle Roll angle of the spacecraft scVelECEF Spacecraft ECEF velocity Second Earth radiometric brightness temperature using internal calibration target (K) UTC second Line-of-sight azimuth angle sensor azimuth angle sensor_view_angle Line-of-sight scan angle 155.1 180.2 205.2 230.3 255.4 280.5 sensor_zenith_angle Line-of-sight zenith angle EU CNIOS SNU02

Show All

Data Min = 155.1, Max = 280.5, Mean = 213.1

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Unified Precipitation Developments



Tomorrow.io Approach to multi-sensor synthesis: Unified Precipitation

Tomorrow.io aims to deliver a seamless global real-time precipitation analysis and Nowcast (rapid-refresh 0-3 hr forecast driven by initial conditions) by blending all available sources (ground radar, spaceborne radar, geostationary imagers, and passive microwave sensors).

This poses many of the same challenges faced by developers of IMERG and other multi-satellite precipitation products:

- Observations with low information content (IR) are spatiotemporally dense
- Observations with high information content (PMW and radar) are spatiotemporally sparse

A machine learning framework, CHIMP (the Chalmers/CSU Integrated Multi-Satellite Retrieval Platform), can accommodate input with these characteristics.



Hurricane Idalia - Gauge Verification

- CHIMP estimates Timing/Magnitude better than other satellite products
- NASA IMERG-Early Calibrated Precip is a poor estimate

Precip Accumulation (mm)

• CHIMP is a significant advancement over the HydroNN system that Tomorrow.io currently runs



Hours



Hours

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Impact of Incorporating Passive Microwave Sensors





GMI

UP: Satellite Precip w/ Sounders						
30 June 2023 Validation w/ GPM CMB	Heidke Skill Score 0.25 mm/h	Heidke Skill Score 12 mm/h				
Current	0.56	0.16				
Next-Gen Geo-Only	0.67	0.36				
Next-Gen + Sounders	0.72	0.65				

An example case demonstrates the potential improvement of the next-generation UP satellite precipitation retrieval model from incorporating orbiting microwave sounders (e.g., GMI, TROPICS). **Nowcast impact will only be positive if the data can be obtained with latency < 1 hr.**

TROPICS



14 Aug. 2023 - Typhoon Lan (Japan)

- Global Satellite Product Verification
- TROPICS Impact







Summary

Tomorrow.io Radar Pathfinder program continues to collect data after more than one year on orbit

- Passive configuration recently implemented
- Just-in-time tasking targets tropical cyclones, buoys (for surface characteritzation), and other precipitation targets of interest
- L2 validation showcases capability of Ka-only radar for precipitation monitoring

Microwave sounder constellation will be coming online over the next year

- 18 payloads being built, launches scheduled through 2025
- Improvements and lessons learned from TROPICS incorporated into design

Improvements coming to real-time and nowcast precipitation

- Testing ML analysis/nowcast shows improvements over IMERG
- WIII begin incorporating near-real-time inputs by EOY 2024



Thank you!





Tomorrow.io Radar Pathfinder Passive Mode





20°N

10°N

- 27.5

- 25.0 -

- 22.5 문

- 20.0 -- 17.5 -- 15.0 -

- 12.5 10.0

10

- Pathfinder is configured to collect two wideband (65 MHz) noise channels outside of the transmit band
- So called "Single-Point" radiometer calibration approaches match our configuration
 - Requires characterization of receiver noise temperature as a function of physical temperature
- Pathfinder receiver was characterized by fitting measurements to simulated brightness temperatures



TMS Instrument Specifications





Orbit Altitude	Swath Width
450 km	1780 km
500 km	2016 km
550 km	2265 km
600 km	2528 km

Channel	TROPICS Center Freq. (GHz)	TROPICS Bandwidth (GHz)	TROPICS NEDT (K)	TMS Center Freq. (GHz)	TMS Bandwidth (GHz)	TMS NEDT Pre-launch Estimate (K)
1	91.65 +/- 1.4	1	0.66	91.65	2	0.38
2	114.5	1	0.96	118.75±3.5	1	0.75
3	115.95	0.8	0.82	118.75±2.625	0.75	0.87
4	116.65	0.6	0.86	118.75±1.875	0.75	0.73
5	117.25	0.6	0.79	118.75±1.25	0.5	0.78
6	117.8	0.5	0.81	118.75±0.75	0.5	0.77
7	118.24	0.38	0.9	118.75±0.375	0.25	1.00
8	118.58	0.3	1.03	118.75±0.125	0.25	0.96
9	184.41	2	0.58	184.41	2	0.54
10	186.51	2	0.55	186.51	2	0.57
11	190.31	2	0.53	190.31	2	0.65
12	204.8	2	0.52	204.8	2	0.63



Band	Beamwidth	Beam Efficiency	FOV* @ nadir	FOV* (scan mean)
W (91 GHz)	2.94°	91.1%	27.7 km	44.3 km
F (114-122 GHz)	2.47°	97.6%	23.5 km	37.6 km
G (184-190 GHz)	1.47°	96.6%	15.1 km	24.2 km
G (204 GHz)	1.44°	97.7%	14.9 km	23.8 km