

Towards Understanding the Uncertainties of PMW-derived Precipitation Regime Trends

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Motivation and Background
Information on rainfall system properties, such as intensity, latent heating, and cloud vertical extent, is of the utmost importance to monitoring, modeling, and hydrology applications. While part of the challenge in providing accurate satellite estimates of these properties lies in the fact that remote sensors can offer only partial and often ambiguous information, a significant contribution to the problem comes from a usually complete absence of information on satellite product uncertainty. The present study seeks to offer analyses of precipitation regimes (convective vs. stratiform) and identify a path towards quantifying the uncertainty level at which some commonly used satellite products provide convective regime estimates.

Data
The study relies on the Global Precipitation Measurement (GPM) passive Microwave Imager (GMI), Dual-Frequency Precipitation Radar (DFPR), and GPM Ground Validation Multi-Radar-Multi-Sensor (GV-MRMS) products to link ECMWF version 5 (ERAS) environmental conditions to the cloud properties and regime state.
• Temporal coverage: GPM era – April 2014 to June 2023.
• Spatial coverage: CONUS and GPM CO domain (60S–60N)
• Resolution: GMI instantaneous Field of View (FOV)
• Products: 2A-CM3-GPM-V07A, 2A-GPM-Ku-V07A

Methods
With a goal to provide an insight and a better understanding of global precipitation systems, their distributions, trends and variability, the study seeks to map precipitation regime agreement between different remote sensors, using common properties of clouds and their surrounding environment.
GV-MRMS, DPR-Ku, and ERAS products are collocated and averaged over the GMI FOVs of 18 and 89 GHz frequency channels.
Where applicable, the precipitation class (convective-stratiform) of each product is assigned based on the convective volume fraction (the ratio of convective to total rain) within the GMI FOV and an arbitrary threshold (0.5).
Snowing and FOVs with GPROF probability of precipitation below 0.15 are excluded from the analysis.
GV-MRMS product precipitation type flags considered for convective class include: Convective, Tropical-convective, and Hail.
Agreement and detection metrics include True Positives (TP), True Negatives (TN), False Positives (FP), False Negatives (FN), and their following derivatives:
 $Accuracy = \frac{TP+TN}{TP+FP+FN+TN}$
 $Sensitivity = \frac{TP}{TP+FN}$
 $Precision = \frac{TP}{TP+FP}$

Precipitation Regime Detection Skill
Figure 1 depicts differences in the relationship between DPR-Ku and GPROF-GMI convective volume fraction (CVF) estimates using GV-MRMS as a reference.

Table 1 summarizes binary class (convective-stratiform) precipitation type assignment by DPR-Ku and GPROF-GMI using GV-MRMS as a reference.

	Accuracy	Sensitivity	Precision	TP	FP	TN	FN	Sample
DPR-Ku	0.86	0.83	0.34	7	12	80	1	1.4e6
GMI	0.86	0.55	0.29	4	11	81	4	1.4e6

The results indicate that non-negligible portion of the convective class detected by the DPR-Ku and GMI is not classified as such by the GV-MRMS product. Explicitly, DPR-Ku estimates align better with the GV-MRMS in detecting the binary precipitation type (convective-stratiform).

Uncertainty Drivers
In a search for uncertainty drivers, the agreement in detection of precipitation class from satellite (DPR-Ku) and ground (GV-MRMS) radars is mapped against the environmental conditions observed during the GPM era (Fig. 2). The agreement is found to be distinct for storms with and without ice-phase (i.e., cold and warm rain).

Detecting Convective Regime Globally
Warm Rain Cold Rain
GMI
DPR-Ku
GMI-DPR-Ku
Fig. 2. Distributions of convective fraction for warm (left) and cold rain (right panels) using the same reference as in the reference.

Linking the Differences to Environment
Fig. 3. Scatter plots of convective regime frequency (convective/total) vs. convective volume fraction (convective/total) for warm and cold rain conditions. Each panel shows the relationship between commonly available proxies for convective intensity is examined next. Figure 3 depicts storm properties and convective fraction dependency on GMI's 89V GHz TB and ERAS 2-meter temperature.

Global Trends of Convective Regimes
GMI
DPR-Ku
Fig. 4. Global trends of convective regime frequency (convective/total) vs. convective volume fraction (convective/total) for warm and cold rain conditions. Each panel shows the relationship between commonly available proxies for convective intensity is examined next. Figure 3 depicts storm properties and convective fraction dependency on GMI's 89V GHz TB and ERAS 2-meter temperature.

Summary
Based on the intercomparisons of GMI pre-bootstrapped DPR-Ku, GPROF-V07 GMI, and GV-MRMS convective fraction estimates, the study seeks understanding of uncertainties in the current remote-sensing techniques for detecting precipitation regimes. GMI-collocated observations, coupled with ERAS environmental conditions, reveal strong differences in the level of agreement between the passive and active microwave sensors for clouds with and without the ice-phase. Proxies of convective intensity (ERAS 2-meter and GMI 89 GHz brightness temperature) are linked to products' agreement in assignment of convective class, revealing the relation between environmental conditions and sensors ability to consistently detect precipitation class. The findings have opened a path towards mapping PMW uncertainties of satellite rainfall trends.

