

Validation of Satellite-based Rainfall Estimation over the Limpopo Basin

By

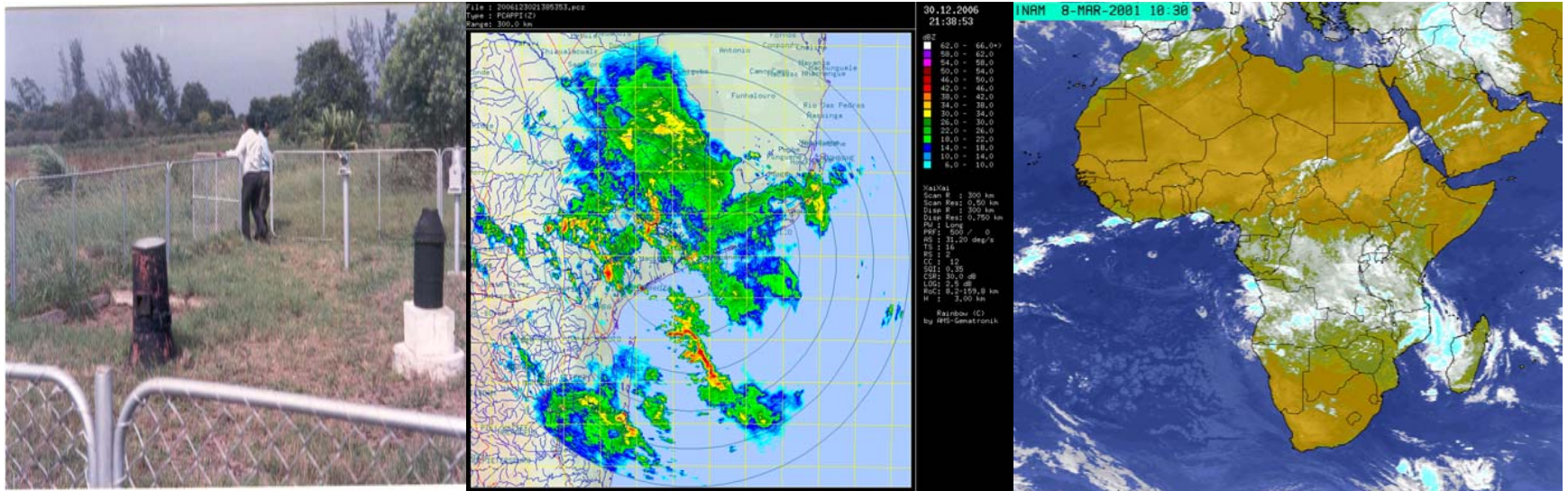
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IPWG / PEHRPP Workshop
WMO Headquarter - Geneva,
3 – 5 December 2007

Presentation Outline

1. Introduction
2. Objectives of the study
3. Methodology
4. Results and discussion
5. Conclusions
6. Recommendations

Acknowledgment



- ❖ **Rain gauge** – true point rain measurement, but is associated to many errors and is sparsely distributed;
- ❖ **Radar** – excellent space/time resolution and observation in real time, however, it requires infrastructures that are expensive;
- ❖ **Satellite** – good spatial/temporal resolution (3 - 5 km/15 - 30min for geostat. Sat.), samples oceans and remote regions.

2. Objectives of the Study

Main objective:

- to investigate the use of satellite rainfall estimation methods over the Limpopo basin.

Specific objectives were:

- To carry out literature survey of existing methods of rainfall estimation using satellites;
- To Generate daily rainfall estimates over the Limpopo basin using satellite based rainfall estimation methods, and
- To validate the satellite based rainfall estimates over the Limpopo basin.

3. Methodology

3.1 Description of the study area



Limpopo basin

Latitude: 20 – 25° S and

Longitude: 25 – 35° E

Southern summer

October to March

*Climate: semi-arid to tropical
temperate*

Aver. Temp.: Max: 30 – 34° C

Min: 18 – 22° C

Precipitation: 200 – 1500 mm



3.2 Satellite rainfall methods used in the study

3.2.1. Climate Prediction Centre Morphing (**CMORPH**) – estimates global precipitation by combining precipitation estimates derived from passive microwave observations and uses spatial propagation information from geostationary data.

Resolution: 30 min / 8 – km at equator;

Spatial coverage: 60° S to 60° N

3.2.2. Multiple Precipitation Analysis (**MPA**)

– is a combination of merged tropical rainfall measuring mission (TRMM) high quality microwaves and the variable rain rate infrared estimates.

Resolution: 3 hrs / 0.25 degrees

Spatial coverage: 50° S to 50° N.

3.2.3. Precipitation Estimation from Remotely Sensed Information using Neural Network (**PERSIANN**) – is an merged estimation method that uses neural network function procedures to estimate rainfall.

- Resolution: 30 min / 0.25 degrees
- Global coverage: 50⁰ S to 50⁰ N.

3.2.4 Naval Research Laboratory Blended (NRLB) – is based upon statistical relationships derived from a precise, near real-time ensemble of colocated passive microwave and infrared data.

- Resolution: 3 hrs / 0.1 degrees
- Global coverage: 50⁰ S to 50⁰ N

3.3 Source of satellite data

Satellite	Type of data	Sensor	Algorithms
Meteosat - 8 (MSG)	IR	SEVIRI	CMORPH, MPA, NRLB and PERSIANN
GOES (9, 10, 12)	IR	VISSR	CMORPH, MPA, NRLB and PERSIANN
NOAA (15, 16, 17,)	PMW	AMSU-B	CMORPH, MPA, NRLB and PERSIANN
DMSP (13, 14, 15)	PMW	SSMI	CMORPH and MPA
TRMM	PMW	TMI	CMORPH, MPA and PERSIANN
Aqua	PMW	AMSU-E	CMORPH and MPA

3.4 Source of rain gauge data

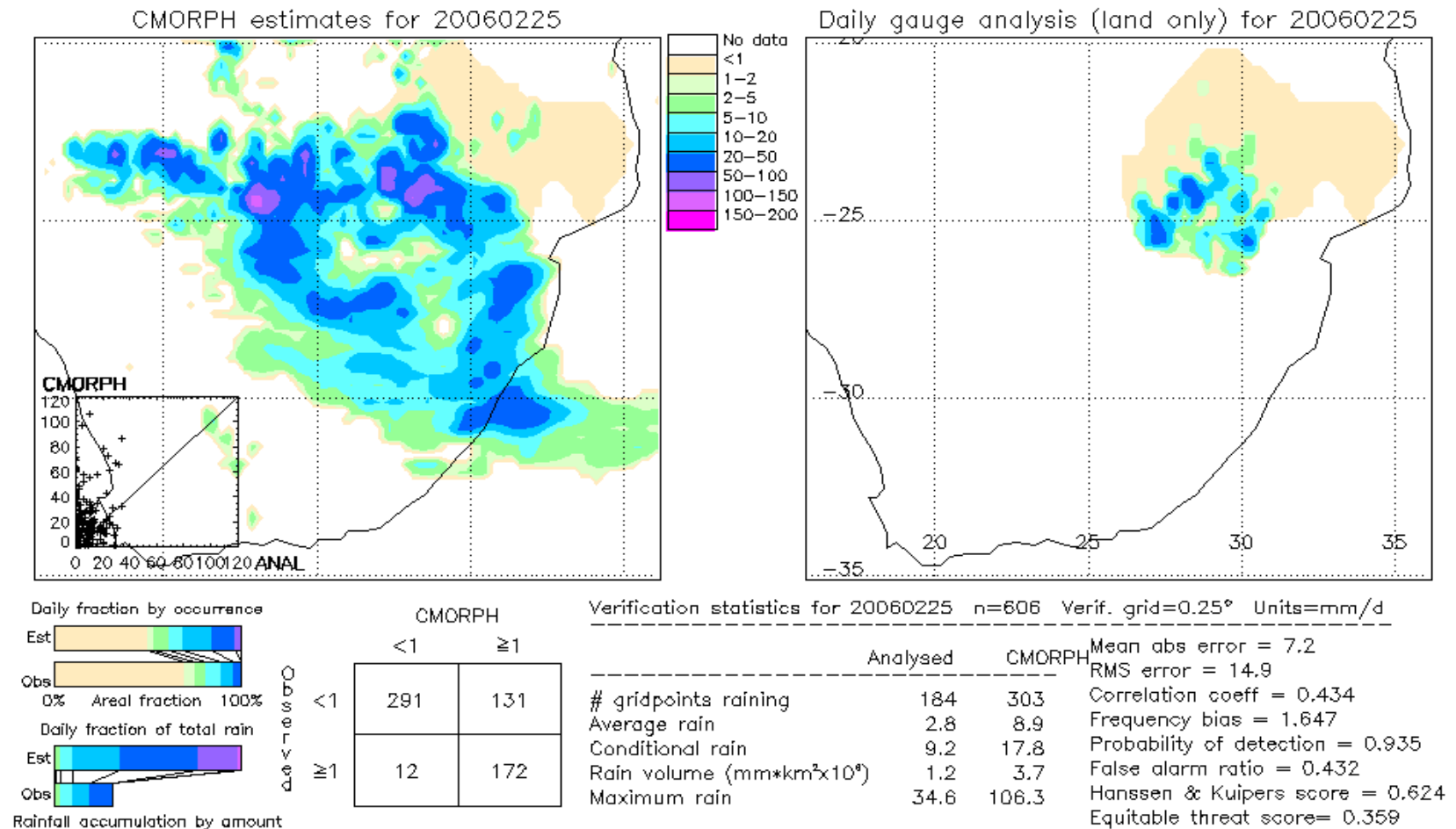
Rain gauge data were obtained from Weather Services of Botswana, Mozambique, South Africa and Zimbabwe (total 90 rain gauge), for 1 October 2005 to 31 March 2006.

3.5 Validation of Satellite Rainfall Estimates

- Rainfall data was averaged into grid boxes of 0.25×0.25 degrees resolution, using the inverse-weighting interpolation method;
- The satellite estimates were developed using 0.25 degree resolution;
- A surface mask was used over the Limpopo basin;
- A variety of statistical parameters were used to measure different aspects of algorithm quality (bias, absol. error, rmse, POD, FAR, ETS, HKS, HSS, and CSI).

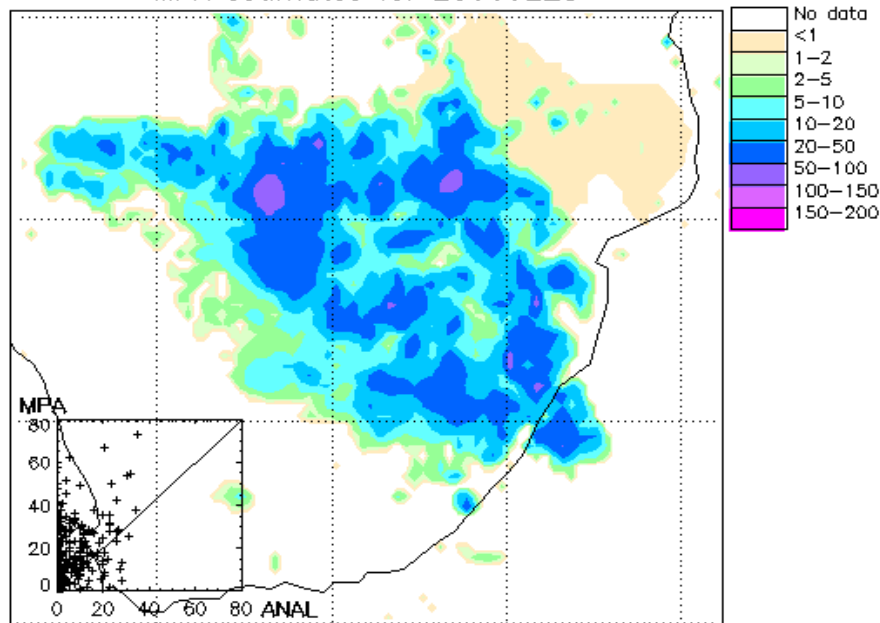
Event Obse		Event estimated		Total obser.
		Yes	No	
	Yes	h (hits)	f (false alarm)	$h + f$
	No	m (misses)	z (correct negative)	$m + z$
	Total estim ated	$h+m$	$f+z$	$h + f + m + z$

4. Results and discussion

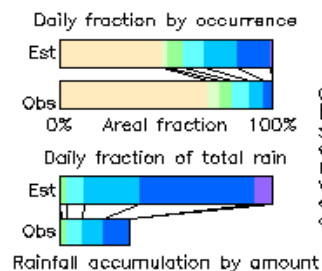
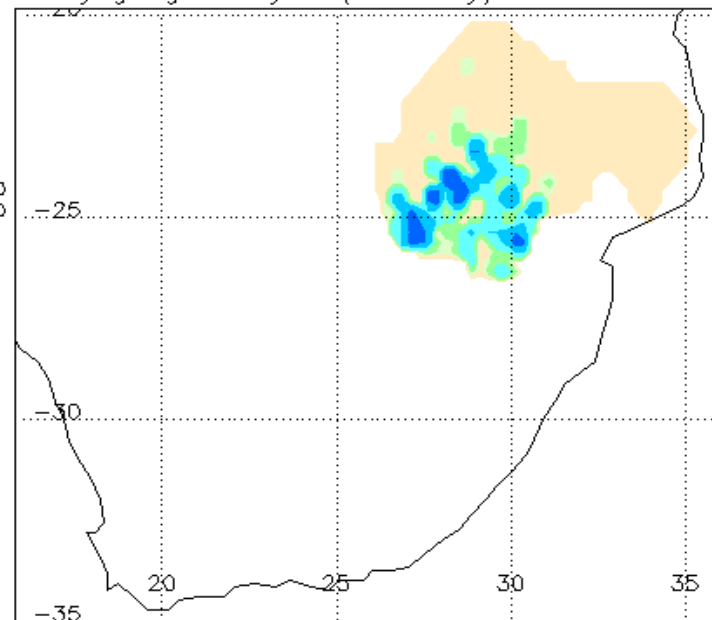


MPA

MPA estimates for 20060225



Daily gauge analysis (land only) for 20060225



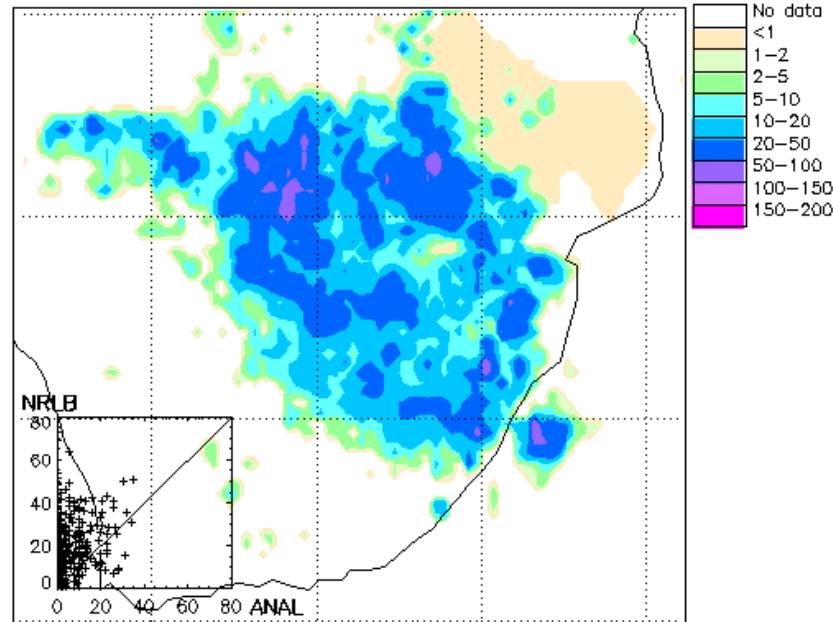
	MPA	
	<1	≥1
<1	290	132
≥1	6	178

Verification statistics for 20060225 n=606 Verif. grid=0.25° Units=mm/d

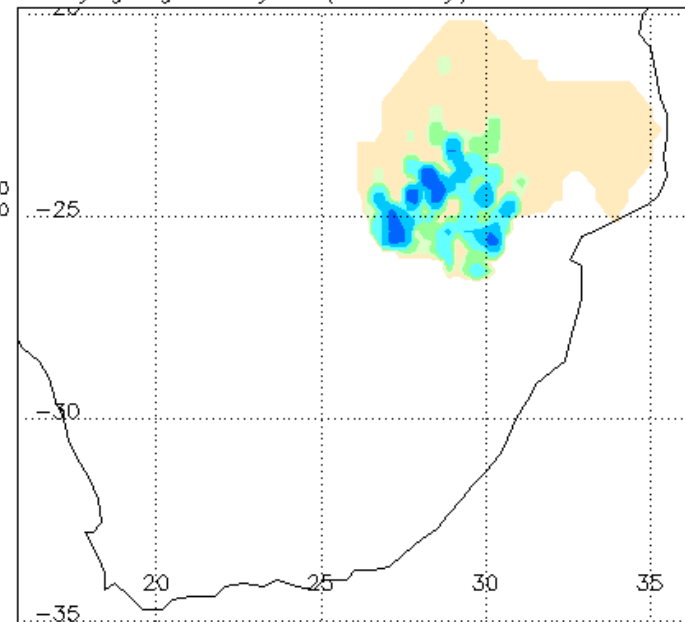
	Analysed	MPA	
# gridpoints raining	184	310	Mean abs error = 6.4
Average rain	2.8	8.5	RMS error = 12.0
Conditional rain	9.2	16.6	Correlation coeff = 0.520
Rain volume (mm*km ² *10 ⁶)	1.2	3.5	Frequency bias = 1.685
Maximum rain	34.6	73.4	Probability of detection = 0.967
			False alarm ratio = 0.426
			Hanssen & Kuipers score = 0.655
			Equitable threat score = 0.378

NRLB

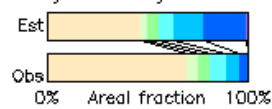
NRLB estimates for 20060225



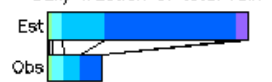
Daily gauge analysis (land only) for 20060225



Daily fraction by occurrence



Daily fraction of total rain



Rainfall accumulation by amount

NRLB

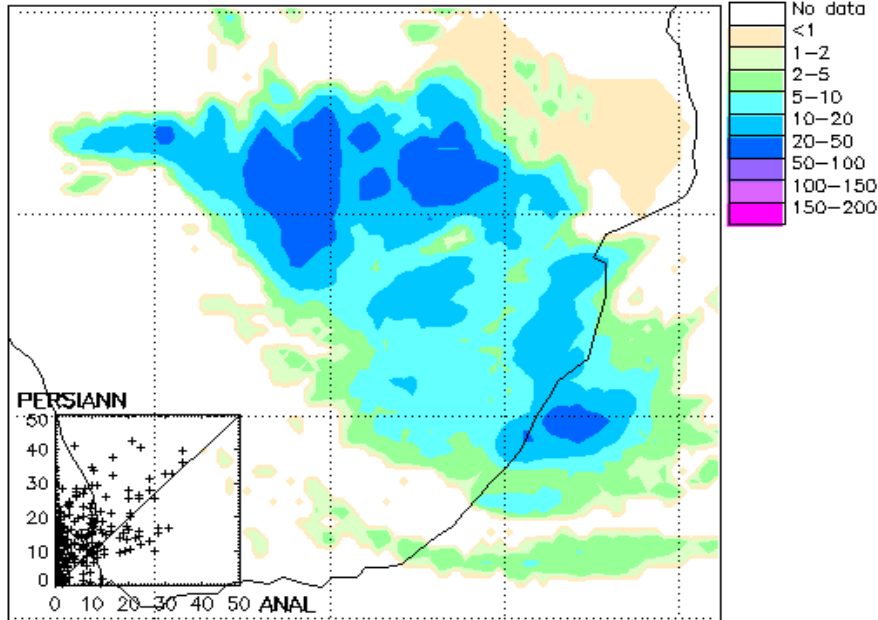
	<1	≥1
<1	276	146
≥1	10	174

Verification statistics for 20060225 n=606 Verif. grid=0.25° Units=mm/d

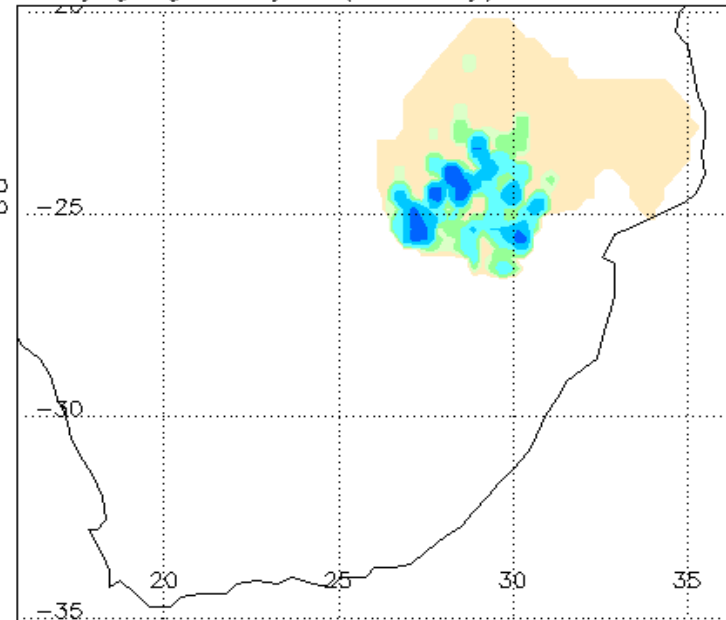
	Analysed	NRLB	
# gridpoints raining	184	320	Mean abs error = 8.1
Average rain	2.8	10.2	RMS error = 14.5
Conditional rain	9.2	19.3	Correlation coeff = 0.424
Rain volume (mm*km ² *10 ⁹)	1.2	4.2	Frequency bias = 1.739
Maximum rain	34.6	72.9	Probability of detection = 0.946
			False alarm ratio = 0.456
			Hanssen & Kuipers score = 0.600
			Equitable threat score = 0.330

PERSIANN

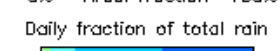
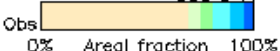
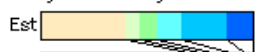
PERSIANN estimates for 20060225



Daily gauge analysis (land only) for 20060225



Daily fraction by occurrence



Rainfall accumulation by amount

PERSIANN

	<1	≥1
<1	243	179
≥1	4	180

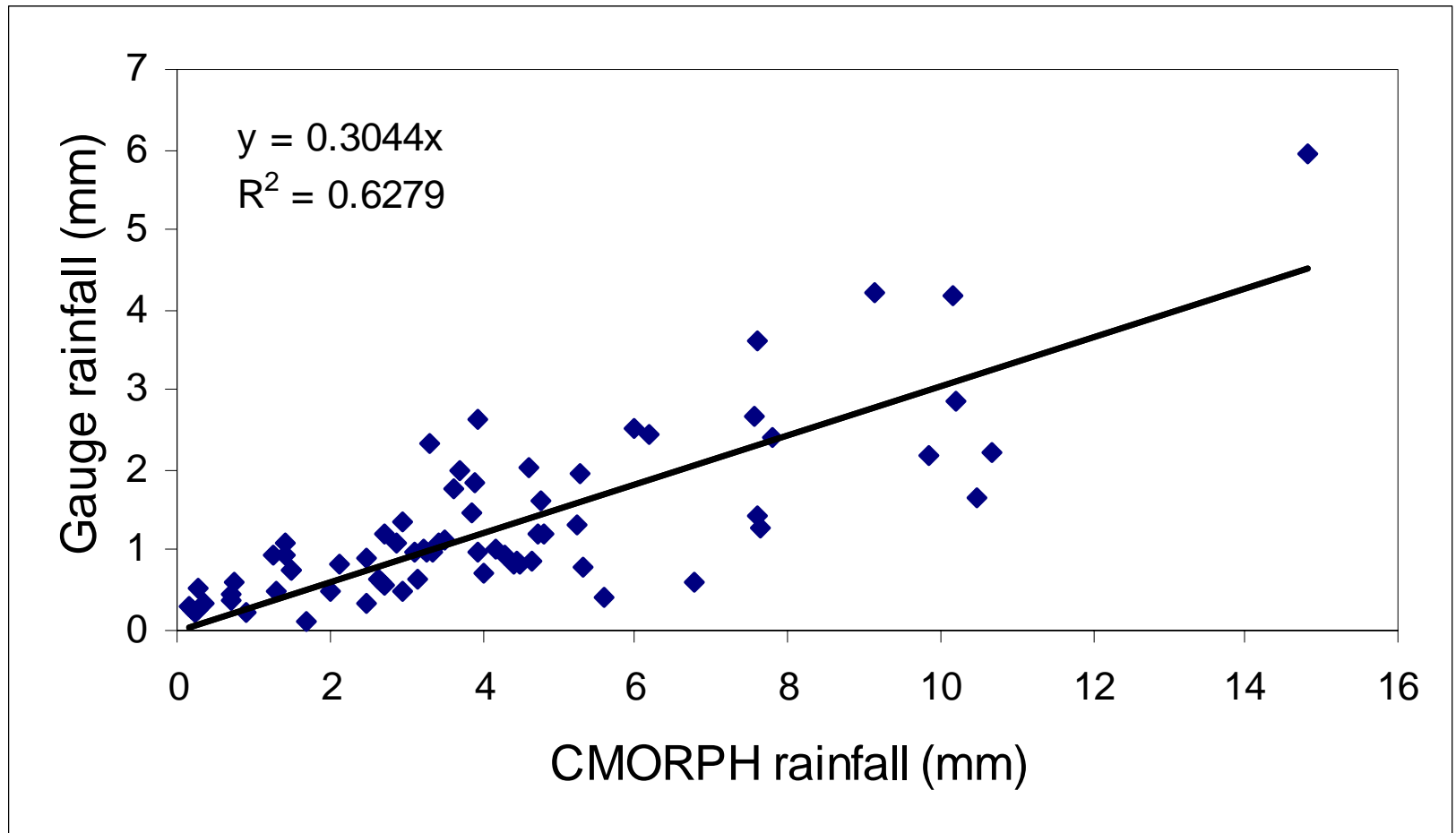
Verification statistics for 20060225 n=606 Verif. grid=0.25° Units=mm/d

	Analysed PERSIANN		
# gridpoints raining	184	359	Mean abs error = 5.6
Average rain	2.8	7.7	RMS error = 9.3
Conditional rain	9.2	12.9	Correlation coeff = 0.535
Rain volume (mm*km ² *10 ⁶)	1.2	3.2	Frequency bias = 1.951
Maximum rain	34.6	42.3	Probability of detection = 0.978
			False alarm ratio = 0.499
			Hanssen & Kuipers score = 0.554
			Equitable threat score = 0.280

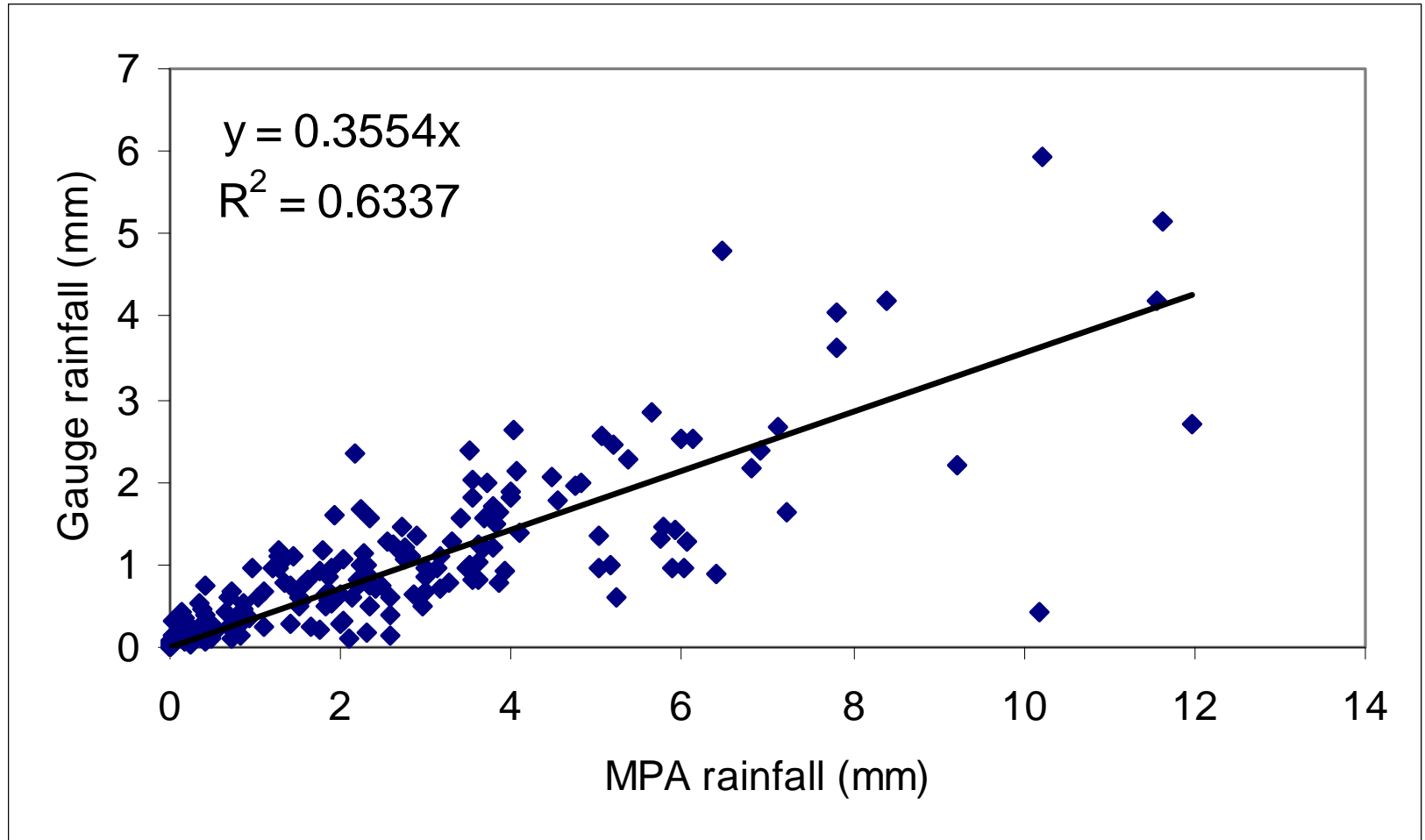
Summary of some statistical parameters for 25 February 2006

Algorithms	Rmse	Bias	POD	FAR	HKS	ETS
CMORPH	14.9	1.6	0.90	0.43	0.62	0.36
MPA	12.0	1.1	0.97	0.43	0.65	0.38
NRLB	14.5	1.7	0.95	0.46	0.60	0.33
PERSIAN N	9.3	1.9	0.98	0.50	0.55	0.28

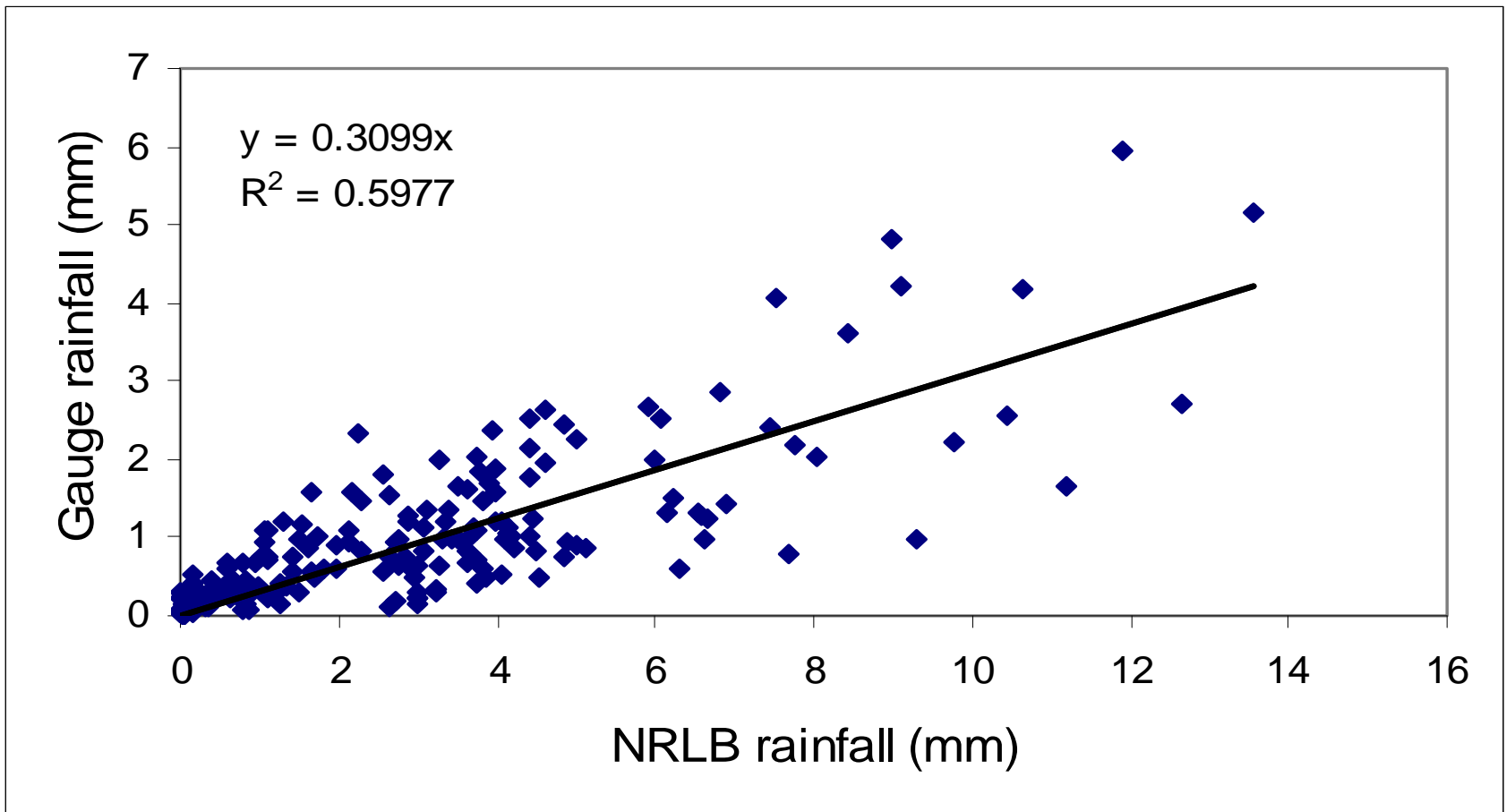
4.1 Comparison between satellite estimates and gauge rainfall



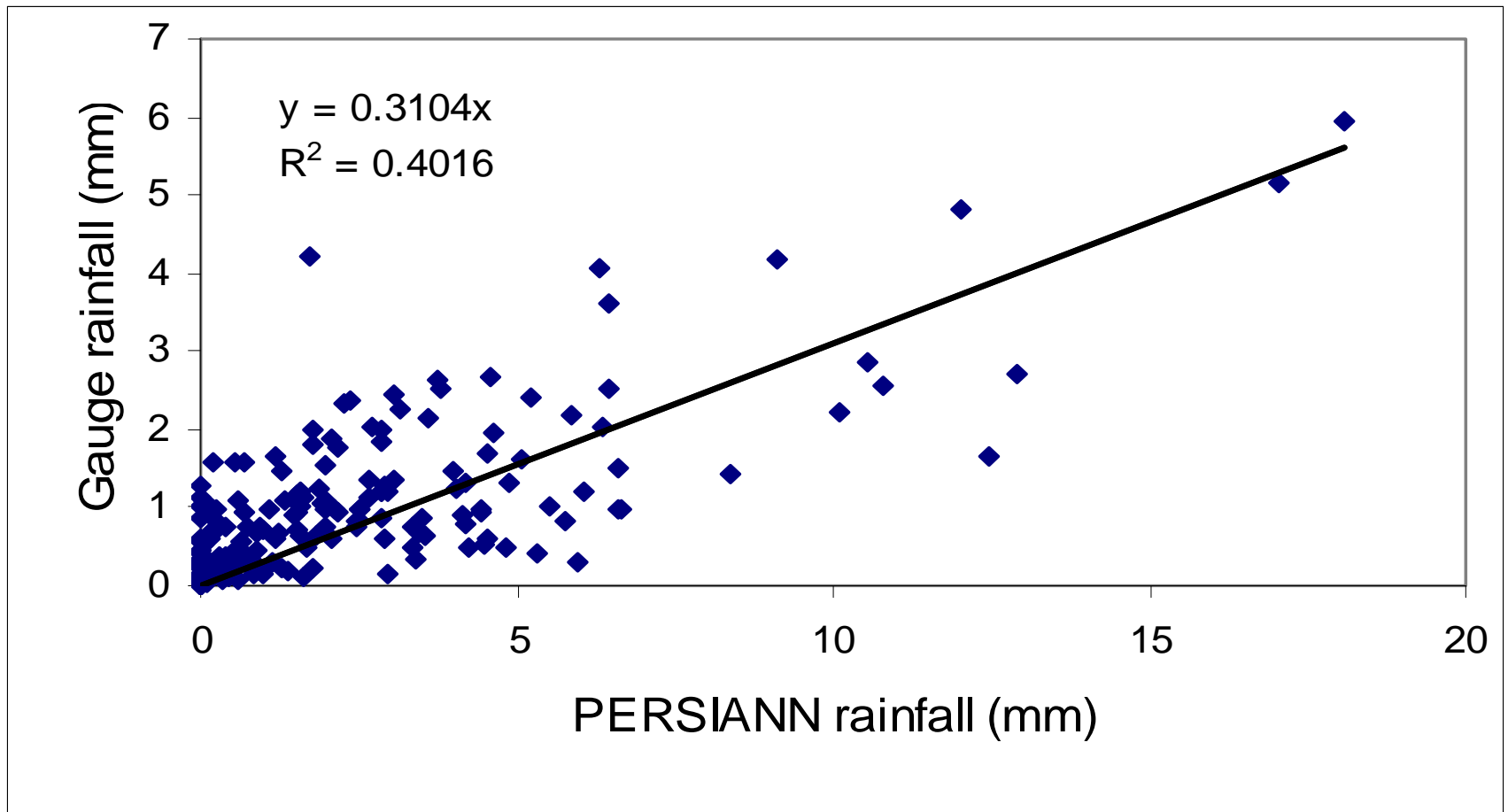
Gauge - MPA



Gauge - NRLB



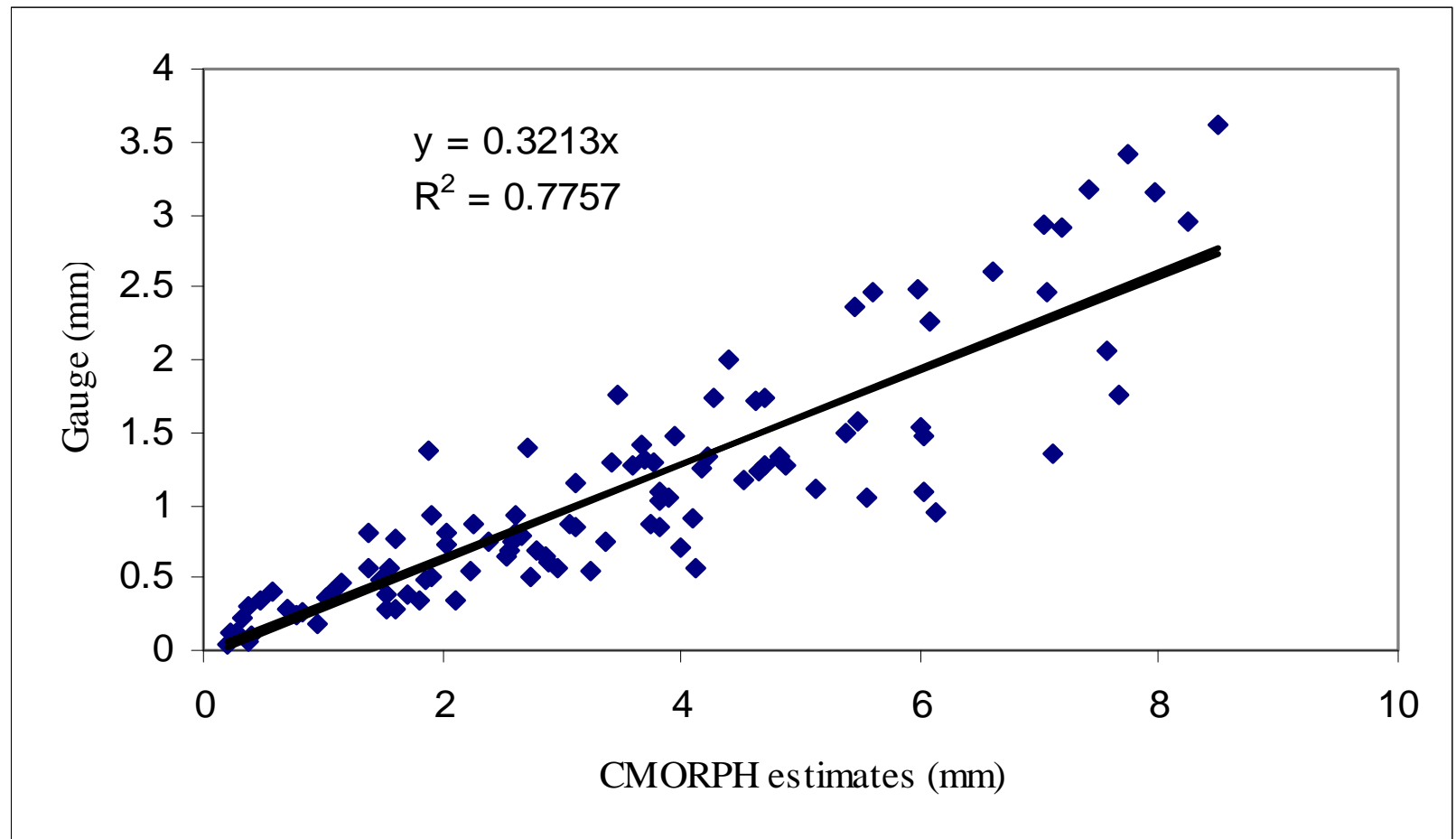
Gauge - PERSIANN

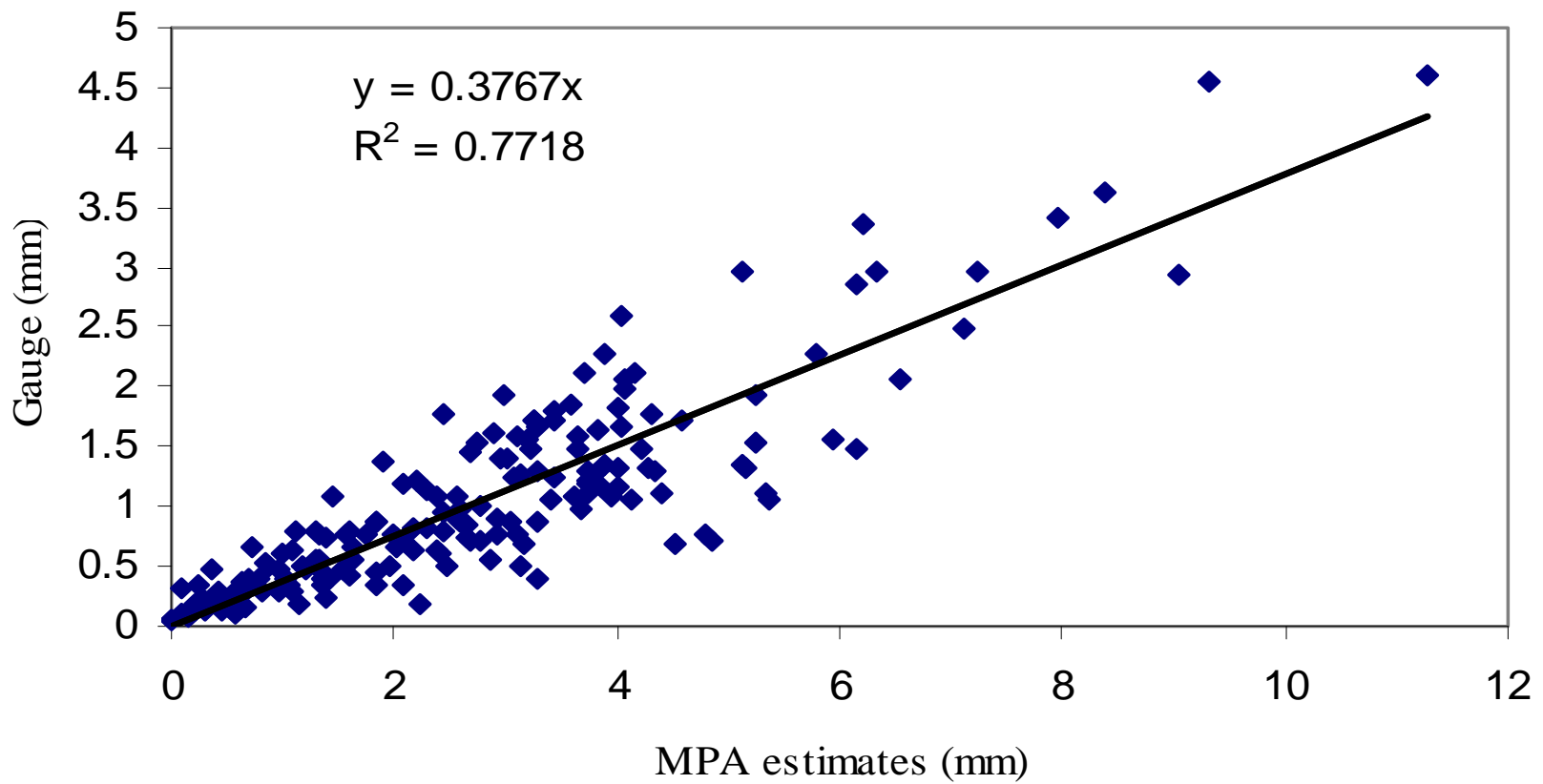


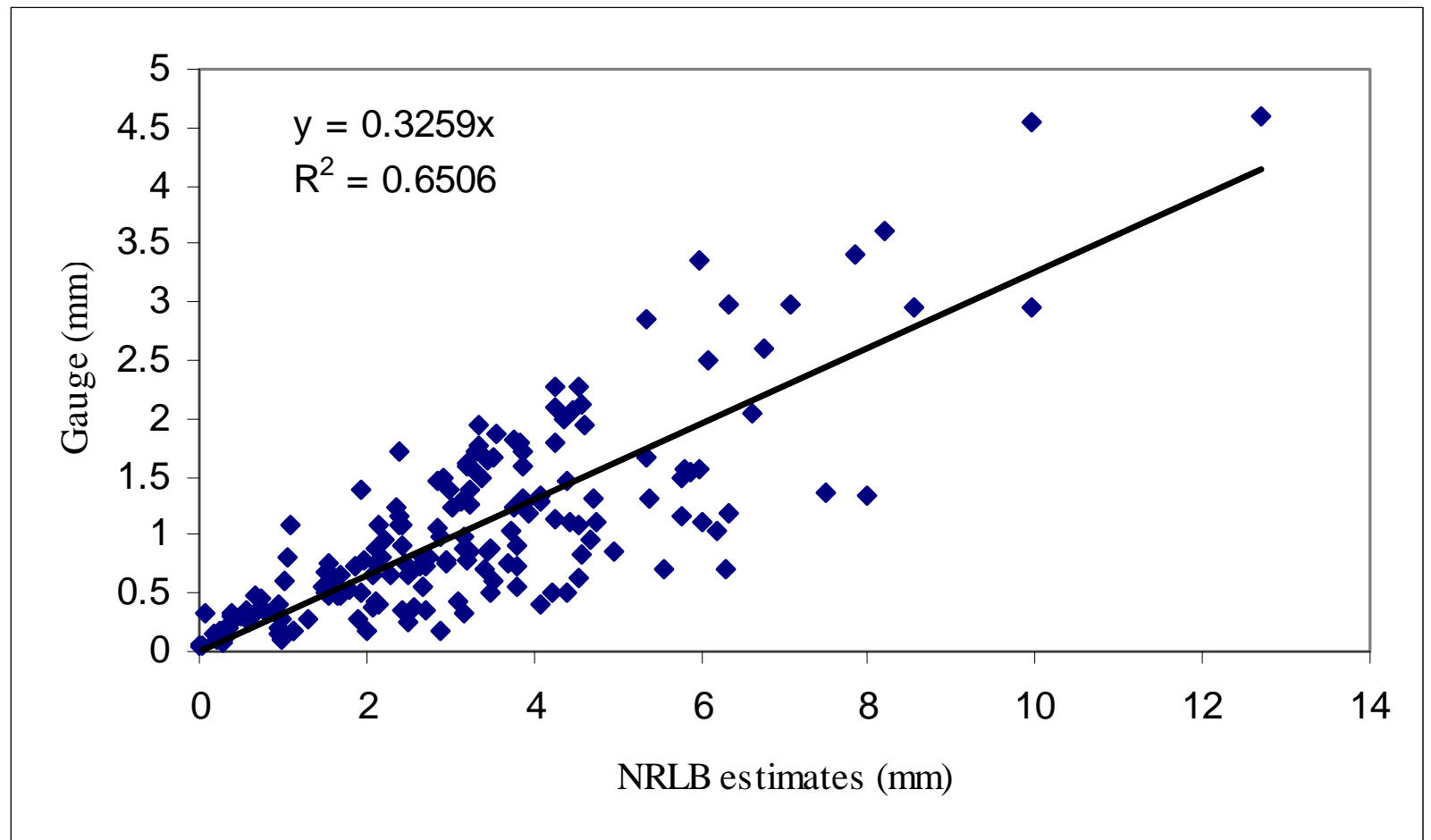
Summary of some statistical parameters for the 2005 / 2006 rainfall season

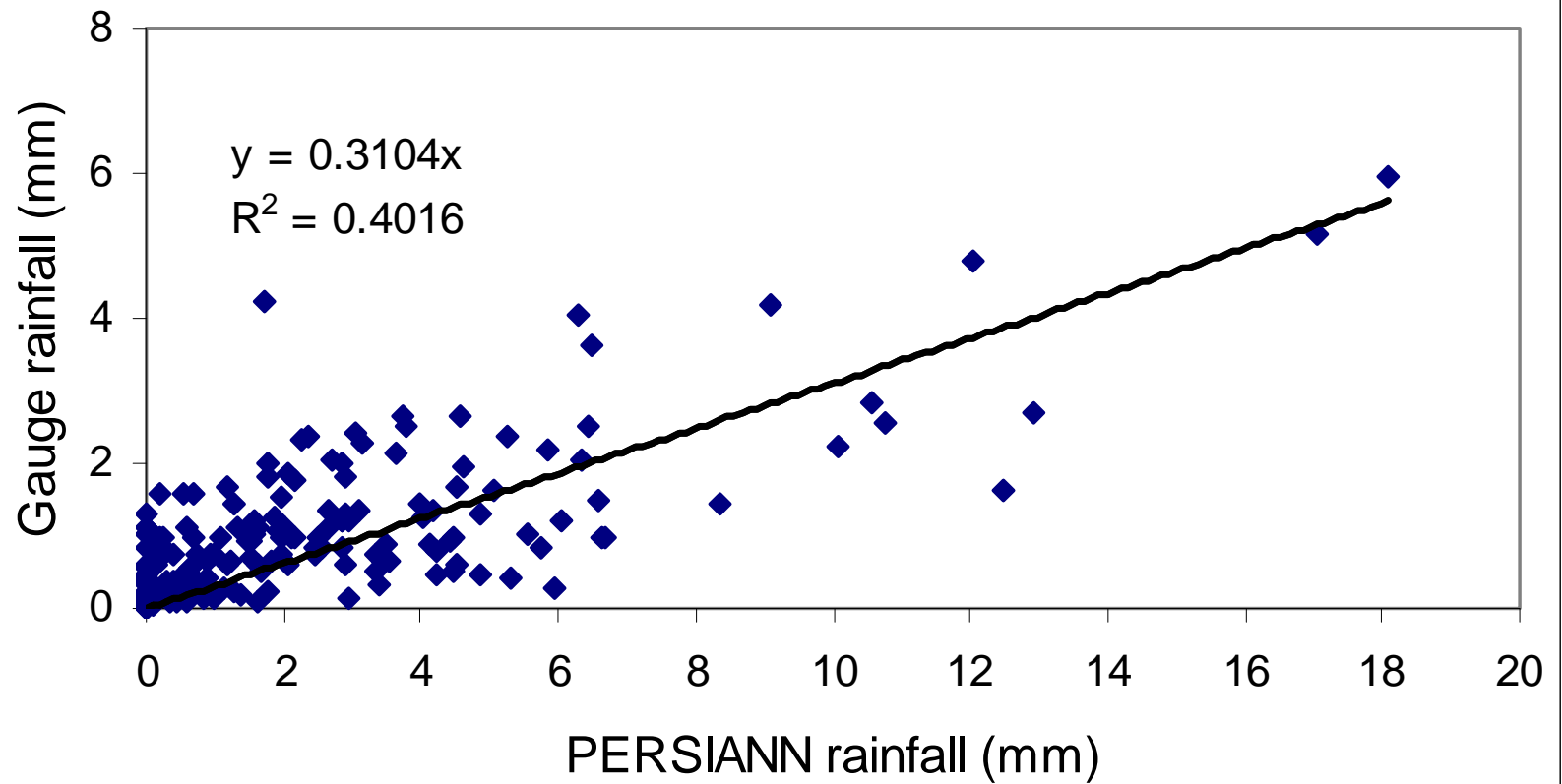
Method	Mean absolute error (mm/day)	Rmse (mm/day)	Bias	R ²
MPA	5.2	6.9	0.4	0.6337
CMORPH	3.6	7.3	0.3	0.6279
NRLB	3.3	8.9	0.3	0.5977
PERSIANN	2.5	5.5	0.3	0.4016

4.2 Comparison between three-daily moving area average and gauge data





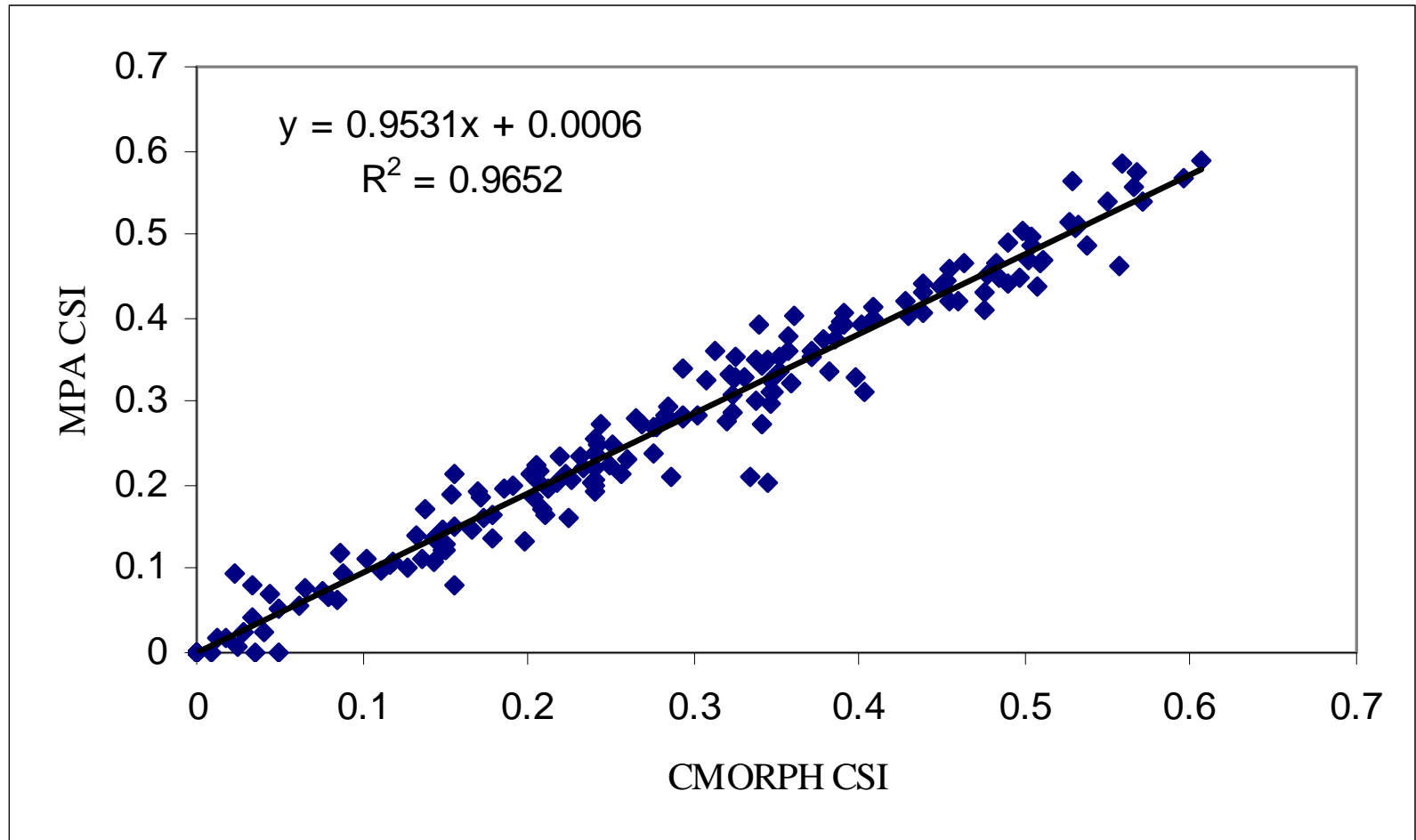


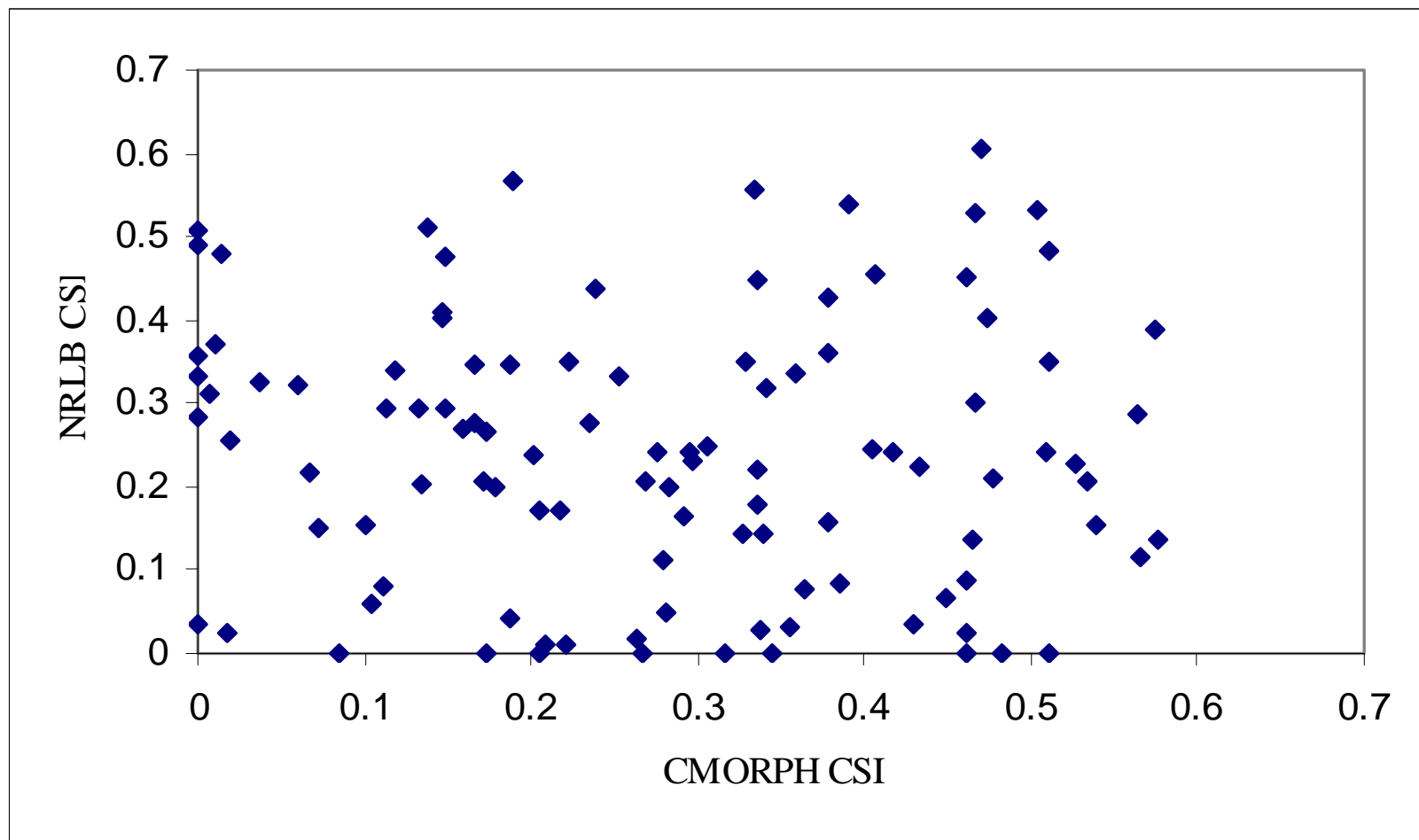


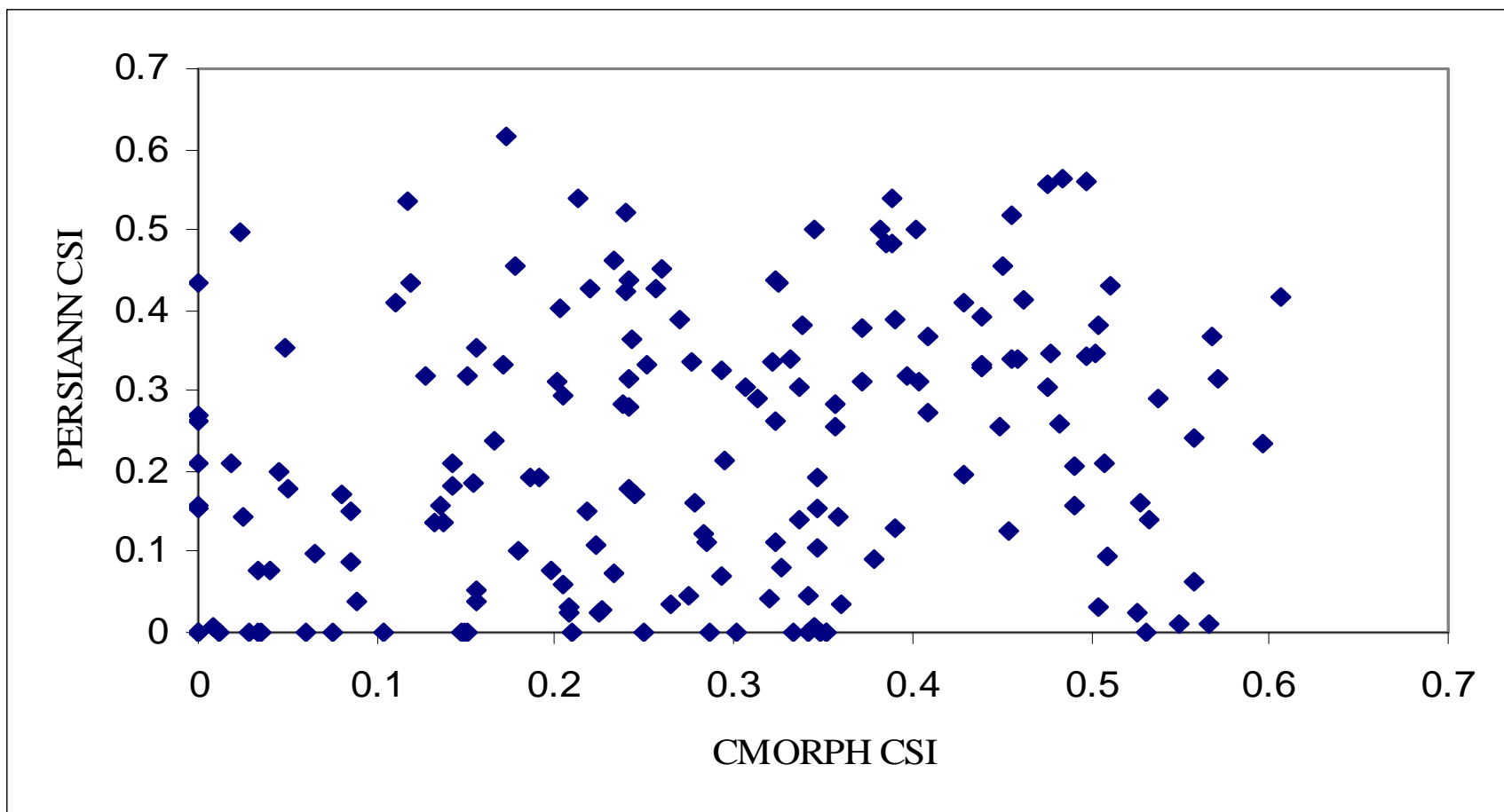
Summary of coefficients of determination

Method	R^2 before moving the daily area average rainfall	R^2 after three daily moving area average rainfall
CMORPH	0.6279	0.7757
MPA	0.6337	0.7718
NRLB	0.5977	0.6506
PERSIANN	0.4016	0.4226

4.3 Analysis of performance of the algorithms







Summary of statistical parameters for the estimation algorithms

Method	POD	FAR	ETS	HKS	HSS
CMORPH	0.91	0.19	0.90	0.29	0.28
MPA	0.89	0.17	0.88	0.26	0.26
PERSIANN	0.89	0.18	0.83	0.21	0.21
NRLB	0.76	0.17	0.60	0.23	0.19

5. Conclusions

- All four algorithms (CMORPH, MPA, PERSIANN and NRLB) showed skill in estimating rainfall and there was relatively good agreement between CMORPH, MPA and NRLB algorithms and fair agreement between PERSIANN and rain gauge (from the values of R-squared);
- CMORPH and MPA performed better than PERSIANN and NRLB, according to the critical success index;

- The accuracy of the algorithms increased with the time after moving three-daily area average gauge;
- All algorithms overestimated rainfall in quantity and spatially over the region with positive values of bias;

- The dry conditions experienced during the 2005 / 2006 rainfall season could have affected the quality of rain gauge data and contributed negatively to the validation of satellite based rainfall estimation algorithms.

6. Recommendations

- To improve the rainfall measurement infrastructures and data exchange within the Limpopo basin between the four countries;
- To carry out similar study during good rainfall season; and
- To validate rainfall estimation by combining gauge, radar and satellite.

Thank you

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Acknowledgement

- International Precipitation Working Group
- World Meteorological organization
- South African Weather Service
- Dr. Joe Turk, Dr. George Huffman,
Dr. John Janowiak and Dr. Ralph
Ferraro
- Alice Blunt

End