Combining radar, satellite and NWP data for precipitation estimation



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Introduction

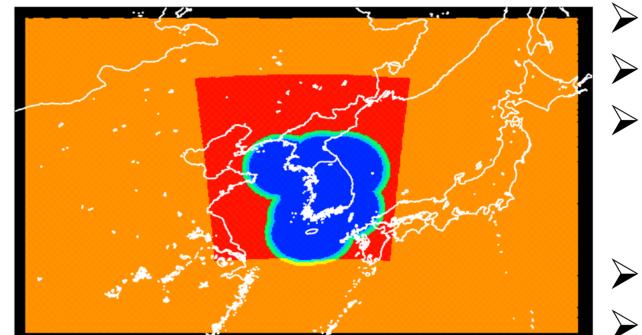
Continuous monitoring and accurate measurements of precipitation are critical for diagnosing and forecasting severe weather and extreme rainfall events. Precipitation measurements can be obtained from a variety of sensors including ground-based radar as well as space-borne sensors. However, precipitation estimation from groundbased radars is limited over land and near coastal regions. This study develops a method merging precipitation estimates over East Asia region from various sensors and models with optimally determined weights.

Merging method

Determine weight coefficients (C_j) of each datasets (radar, satellite and model precipitation) from optimal weight merging method.

- The edge of radar observation area is used for reference data.
- Determine weight coefficients from root mean square error with reference radar data.

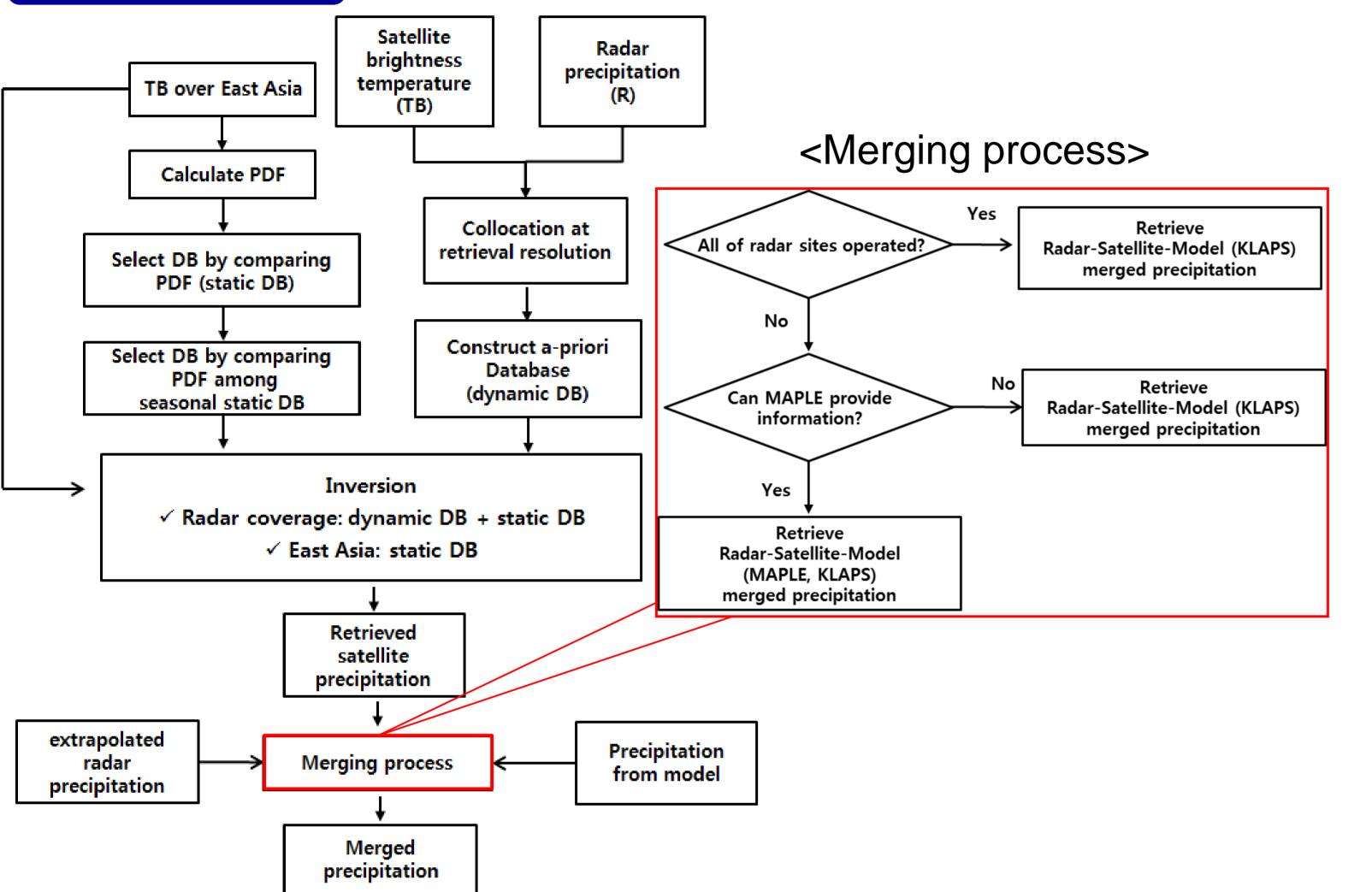
<Merging mask >



- Blue: radar observing area.
- Green: radar data uses as reference data.
- Red: KLAPS forecasting area.

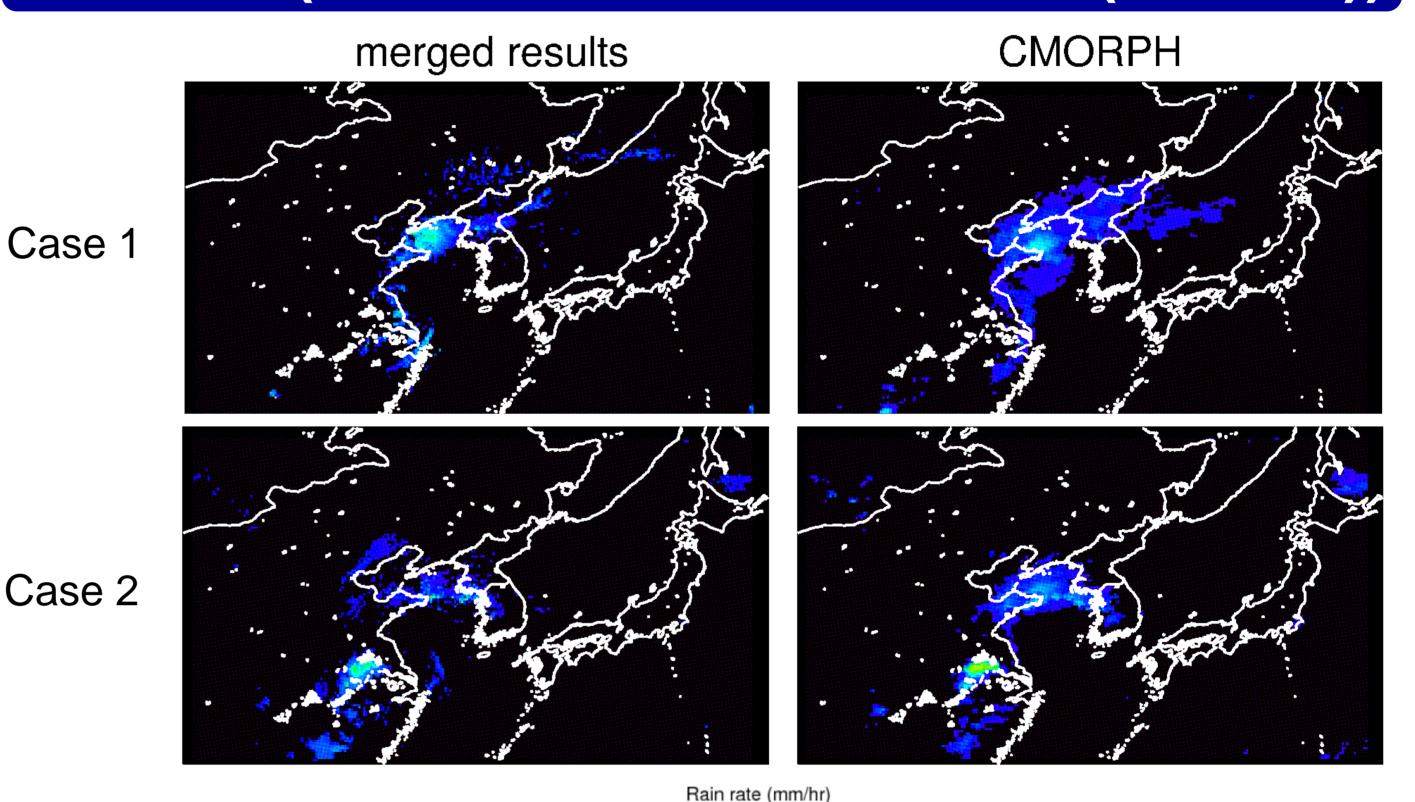
radar-satellite-model combined precipitation

Flowchart



can be produced at inside the red box.
➤ Yellow: radar-satellite combined precipitation
➤ Orange: only satellite precipitation

Results (radar + satellite + model (KLAPS))



• Merged precipitation is generated over East Asia region, and

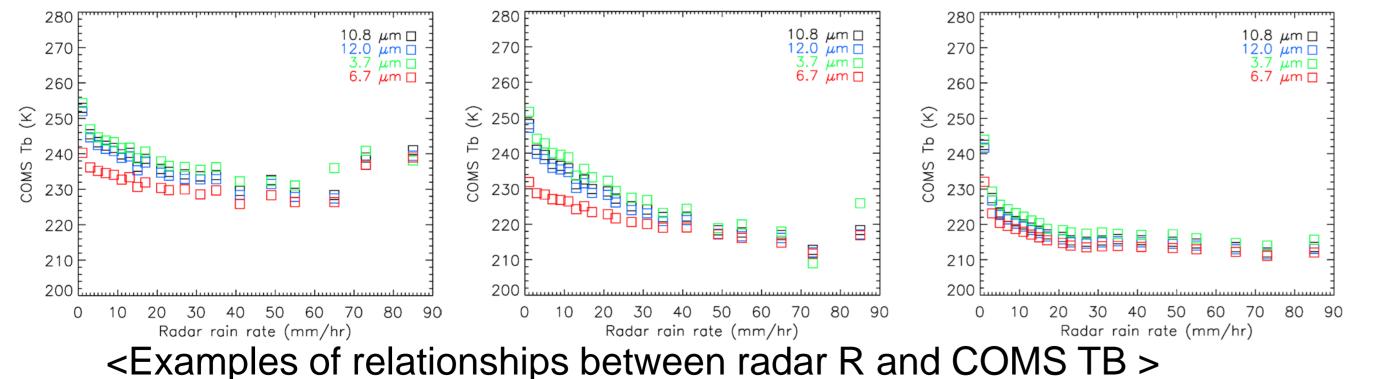
20.0

Data

- Radar: CAPPI 1.5km over Korean peninsula
- Satellite: retrieved precipitation from COMS (Communication, Ocean, and Meteorological Satellite).
- Model
 - KLAPS (Korea Local Analysis and Prediction System)
 - ✓ Based on numerical model
 - ✓ Forecast near Korean peninsula
 - MAPLE (McGill Algorithm for Precipitation nowcasting and Lagrangian Extrapolation)
 - ✓ Extrapolation-based model
 - ✓ Forecast over radar observing area

Satellite precipitation estimation

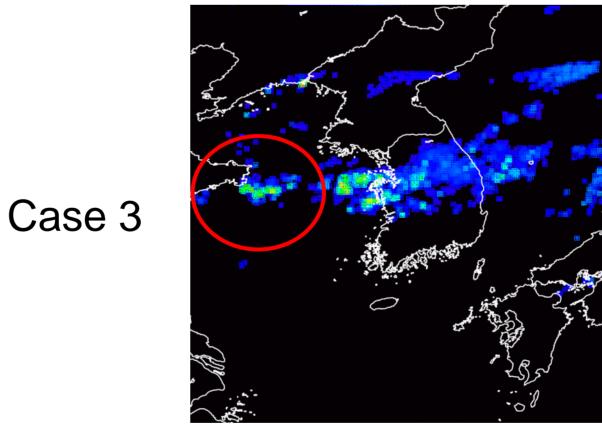
The satellite precipitation estimation greatly relies on the diverse relationships between rain rates (R) and brightness temperatures (TB) included in a-priori databases.

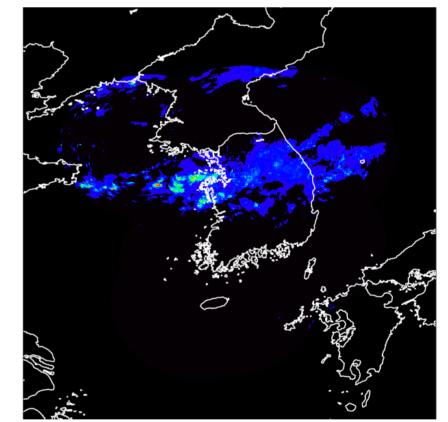


compared to independent satellite precipitation product (CMORPH).

30.0

Results (radar + satellite + model (KLAPS, MAPLE))





<Merged result when Baengyeong-radar (west part of Korean peninsula) did not operate>

<Radar estimated precipitation at 10 minute after the case 3. (Baengyeong-radar operates)>

 Merged precipitation shows rain rate where radar did not operate but MAPLE predicted precipitation exists.

Summary and ongoing work

- A method is developed to merge precipitation estimates from various sensors and models with optimally determined weights.
- The databases were built with the temporally and spatially collocated brightness temperatures at three channels (6.7, 10.8, and 12 μ m) of the COMS and ground-based radar rain rate estimates.
- The database showing the most similar probability density function (PDF) of TB to that of the observed TB is first selected.
- Through the Bayesian inversion (Rodgers, 2000), satellite estimated precipitation is retrieved.

- As an elements of the merging, satellite precipitation is estimated based on radar R - satellite TB relationships of a-priori databases.
- The merging methodology can include additional precipitation estimates such as microwave based product.
- Since the model (KLAPS) simulated rain has a problem of incorrect location and intensity, the optimal estimation based precipitation data is produced to replace KLAPS.

Acknowledgement

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