

Surface Deformation Measurements Scientific Requirements & Challenges

1st Science and Application Workshop
for Germany-Japan Next-Generation SAR

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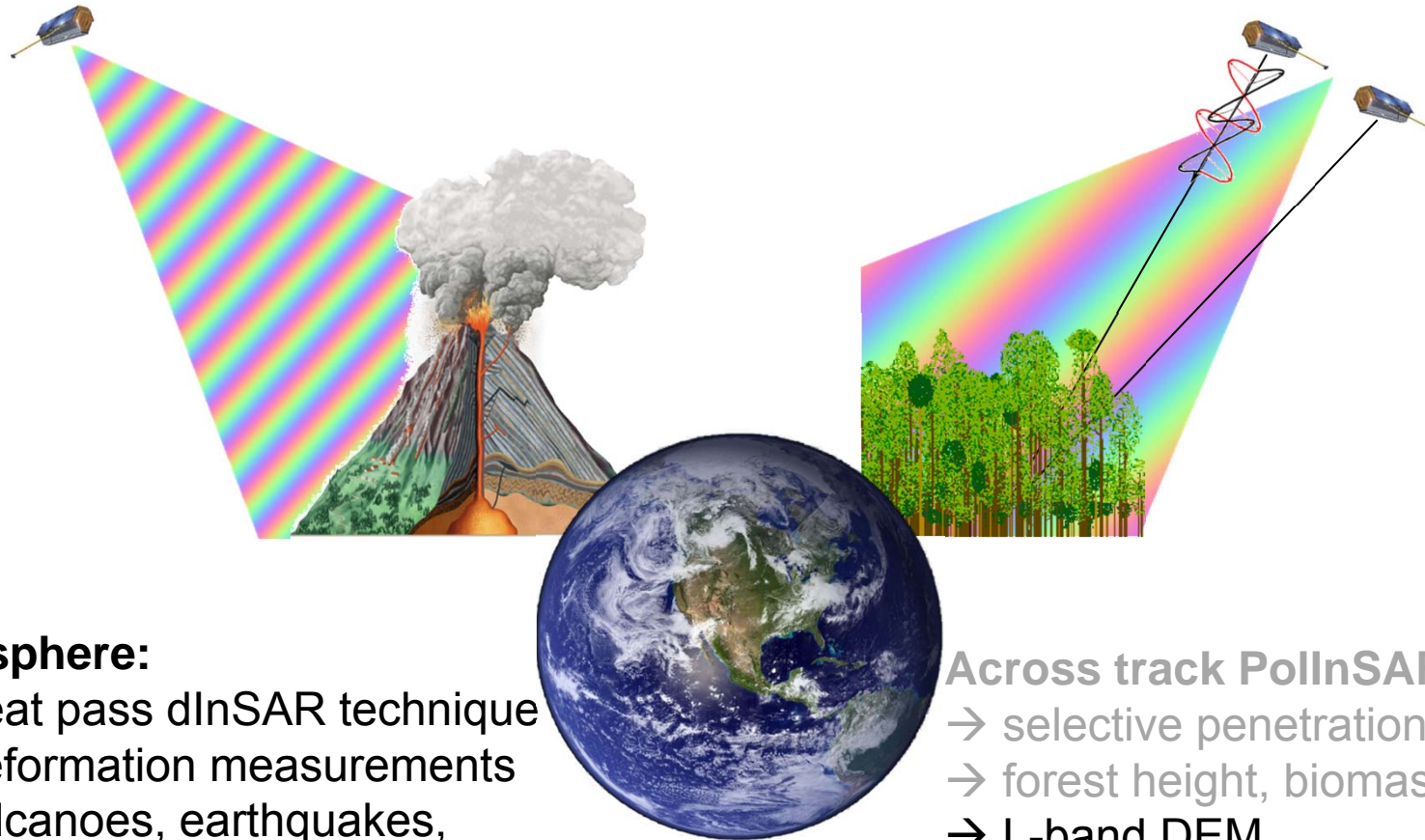
Tokyo, 27.6.2013



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Tandem-L Mission: Two Operation Modes



Geosphere:

Repeat pass dInSAR technique
→ deformation measurements
of volcanoes, earthquakes,
tectonic, cities, CCS

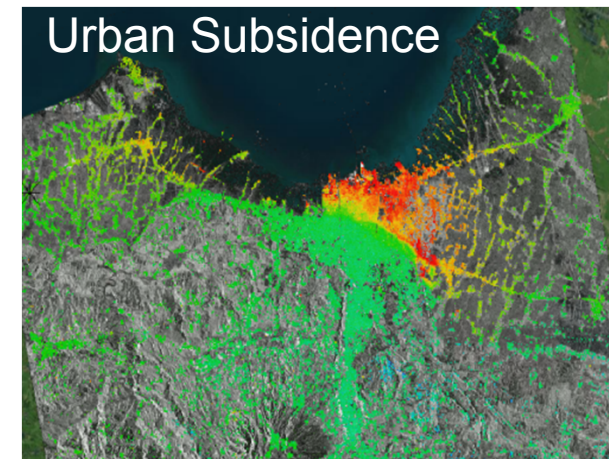
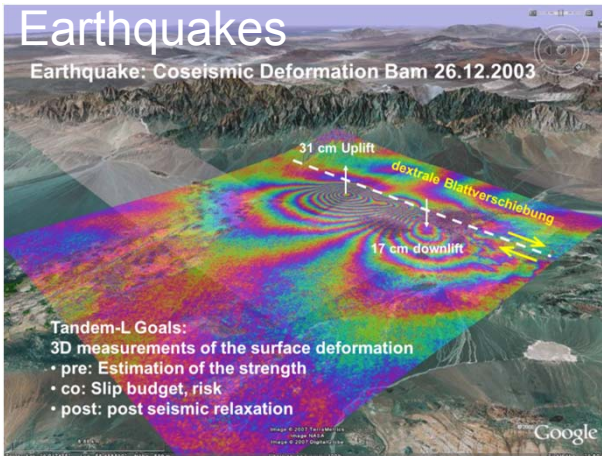
Across track PolInSAR technique

→ selective penetration
→ forest height, biomass
→ L-band DEM



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Applications Driving Geosphere Requirements





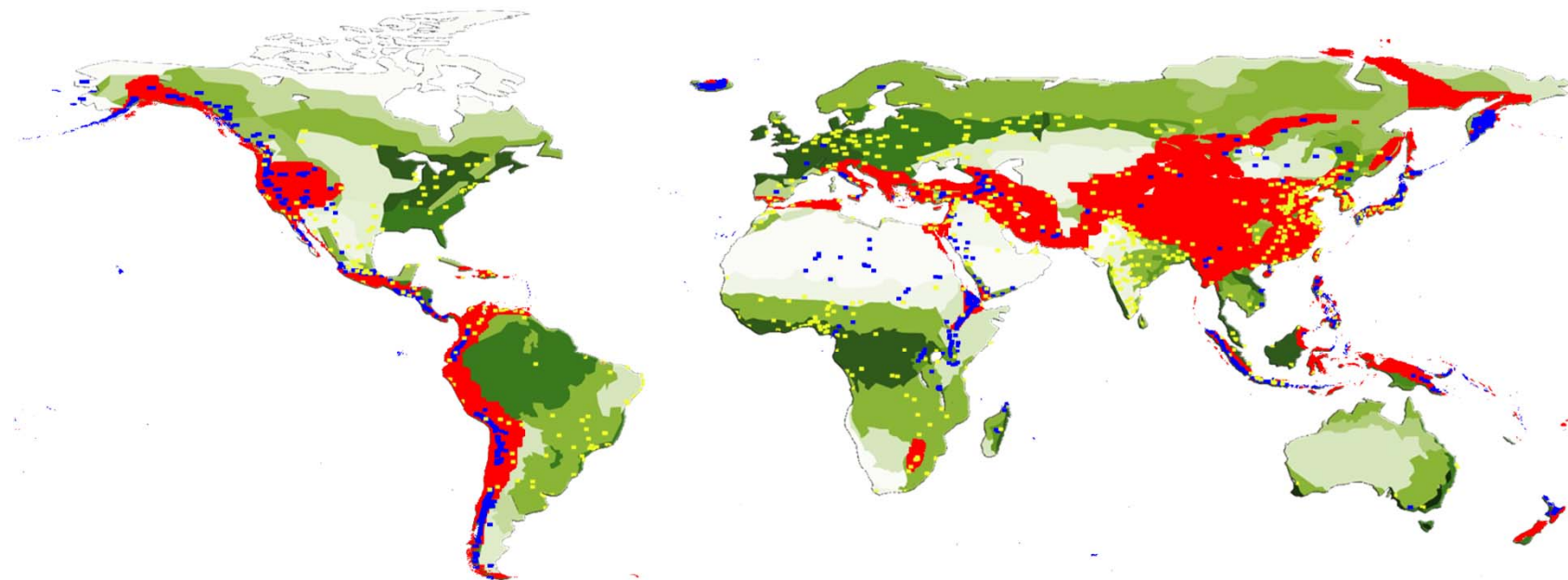
Motivation

- Many InSAR examples have been shown - exciting technique - but results opportunistic (selected) and incomplete
- Why?
 - Temporal decorrelation, e.g. TerraSAR-X, ERS, ASAR
 - Insufficient coverage, e.g. TerraSAR-X
 - Infrequent revisit: ALOS-PALSAR
 - Improper viewing geometry: 1D, layover, ...
 - Non-systematic data evaluation
- Challenge: operational & systematic & accurate Earth surface motion monitoring with an InSAR system tailored to needs (cf . SRTM, TanDEM-X):
 - Tandem-L German study / proposal (Moreira et al.)
 - ➔ German Helmholtz Study
 - ➔ JAXA Study





Tandem-L Requirements: Coverage



Green: biomass/forest areas (different heights)

Red: weekly high strain areas (UNAVO+seismic)

+ four global deformation images / year,

Blue: weekly volcanos

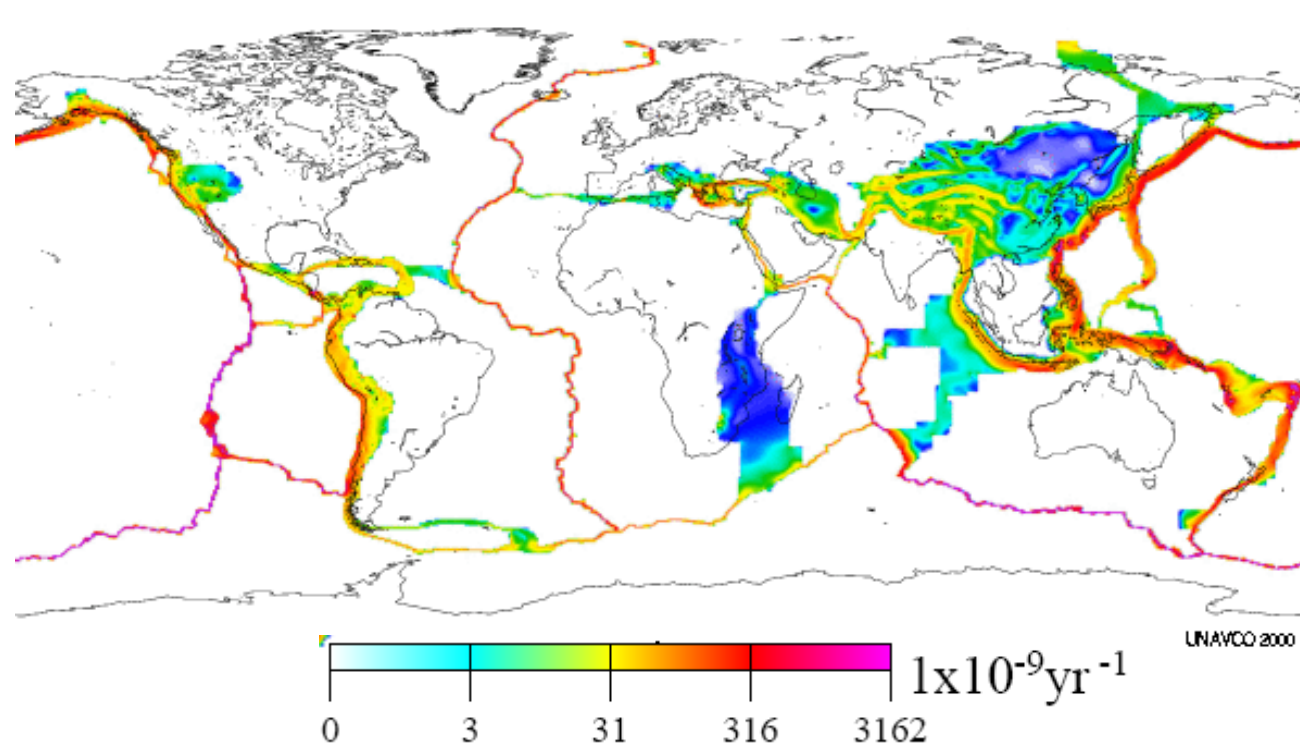
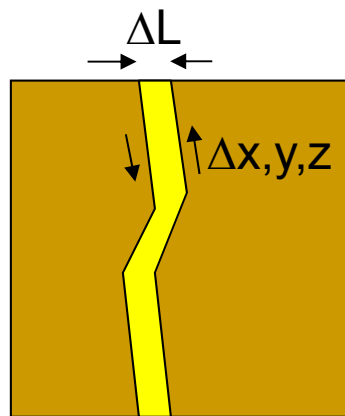
Yellow: weekly cities

+ TBD weekly landslides, CCS sites, etc.



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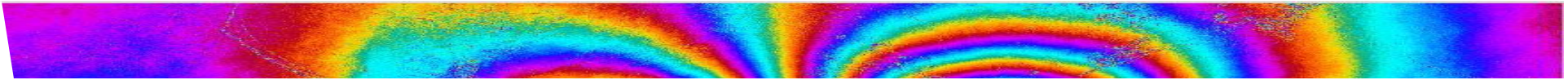
Accuracy Challenge: Small Interseismic Strain Rates



Requirement formulation: $\Delta x = 1 \text{ mm}$, $\Delta L = 30 \text{ km}$, $\Delta t = 1 \text{ year}$, 1-5 y measurement

$$\text{strain_rate} = \frac{\Delta x}{\Delta L \Delta t} = 33 \cdot 10^{-9} \text{ y}^{-1}$$





Requirements (Generalized & Compressed)

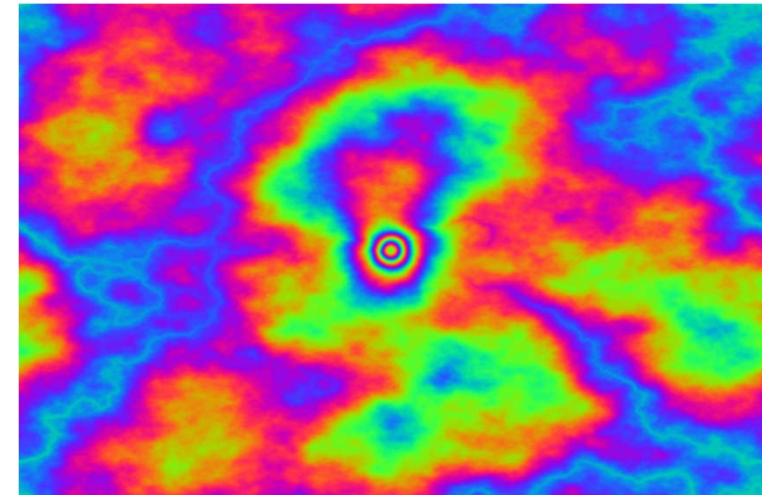
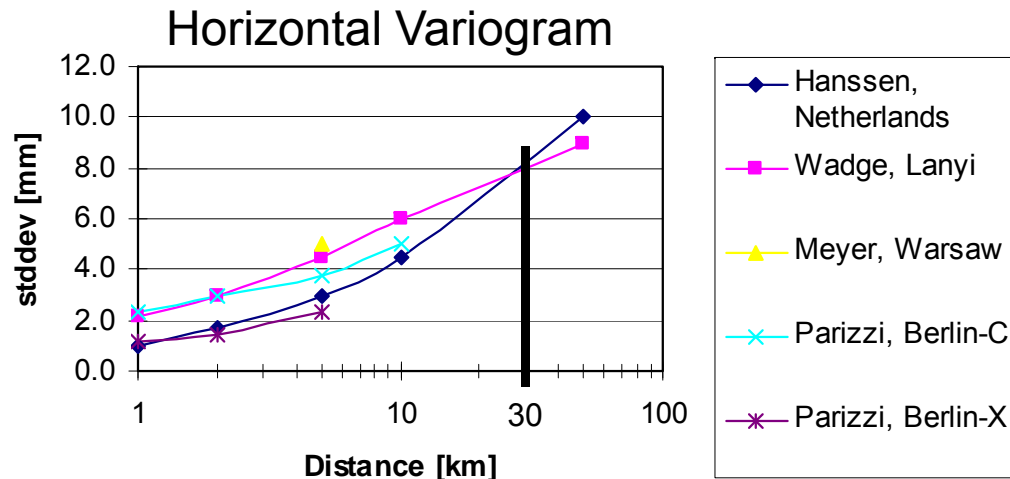
	<i>Displacement Accuracy</i>	<i>Imaged area</i>	<i>Resolution</i>	<i>Frequency</i>
Global	1cm/50km (5a)	approx. 150 Mio. km ²	50 m	4/year
Earthquakes	1mm/30km (5a) or better 3D-Vector	approx. 25 Mio. km ²	10-50 m	up to 4/week
Volcanoes	cm-range 3D-Vector	approx. 5 Mio. km ²	50 m (→1-2 m?)	weekly
Anthropogenic deformation	mm/cm-range	Metropolitan areas	20 m (→1-2 m?)	monthly
Landslides	cm-range 3D-Vector	Selected mountainous regions	20 m	1-4/month

+ DEM times series (from TanDEM-X experience)

(→1-2 m?): Demand for higher resolution (from TerraSAR-X exp.)



Biggest Challenge: Atmospheric Water Vapor



Comparison of reported atmospheric zenith delay InSAR phase errors

1. R. Hanssen, Radar Interferometry, Kluwer, Dordrecht, 2001
2. F. Meyer, R. Bamler, R. Leinweber, J. Fischer, A Comparative Analysis of Tropospheric Water Vapor Measurements from MERIS and SAR, Proc. of IEEE IGARSS 2008
3. EVINSAR, Proposal for an ESA Earth Explorer Mission, G. Wadge
4. Parizzi, GITEWS Project (DLR internal TN)

→ + high vertical stratification!

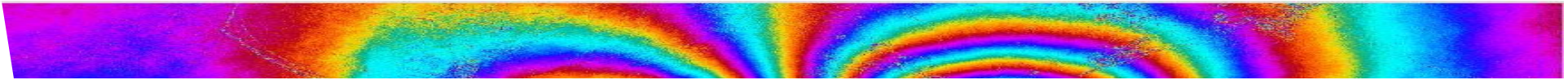
Countermeasures:

→ >1 year data averaging: PSI (€€€!)

→ Low res tropospheric model for correction of vertical stratification

→ High res. tropospheric model for correction of horizontal variation TBD?

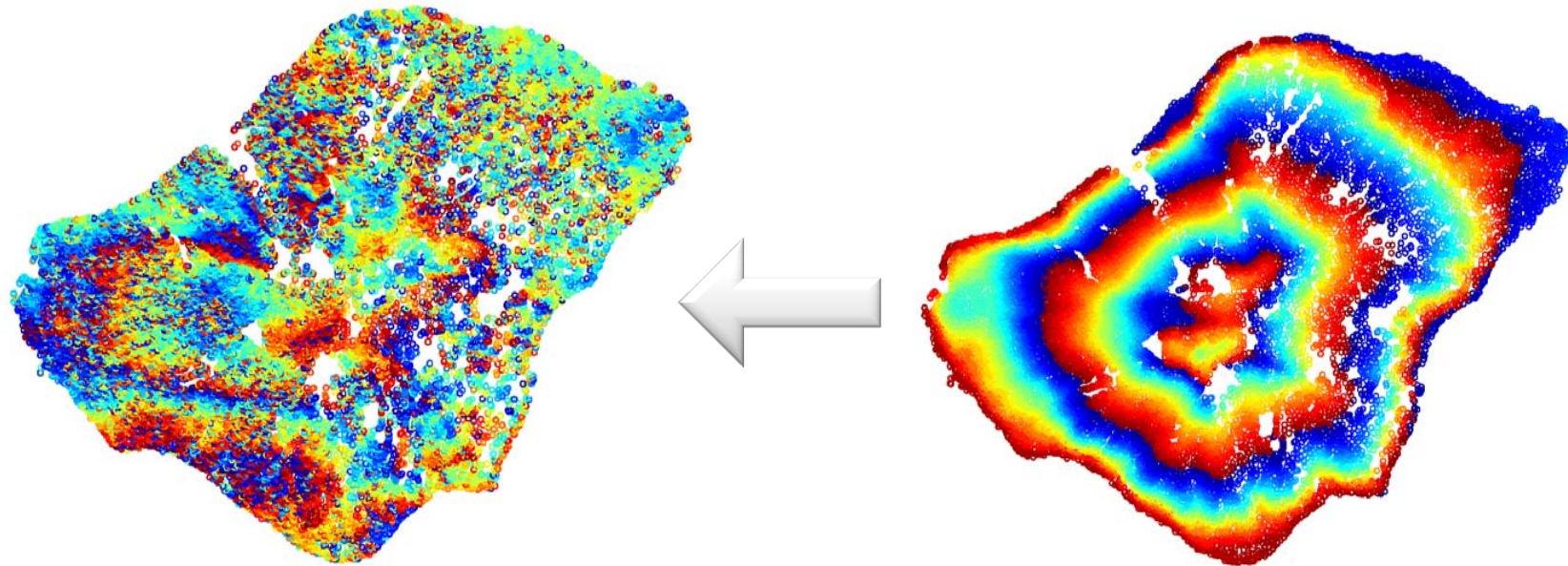




Compensation of Stratified Atmospheric Delay

Corrected PS Differential Phase

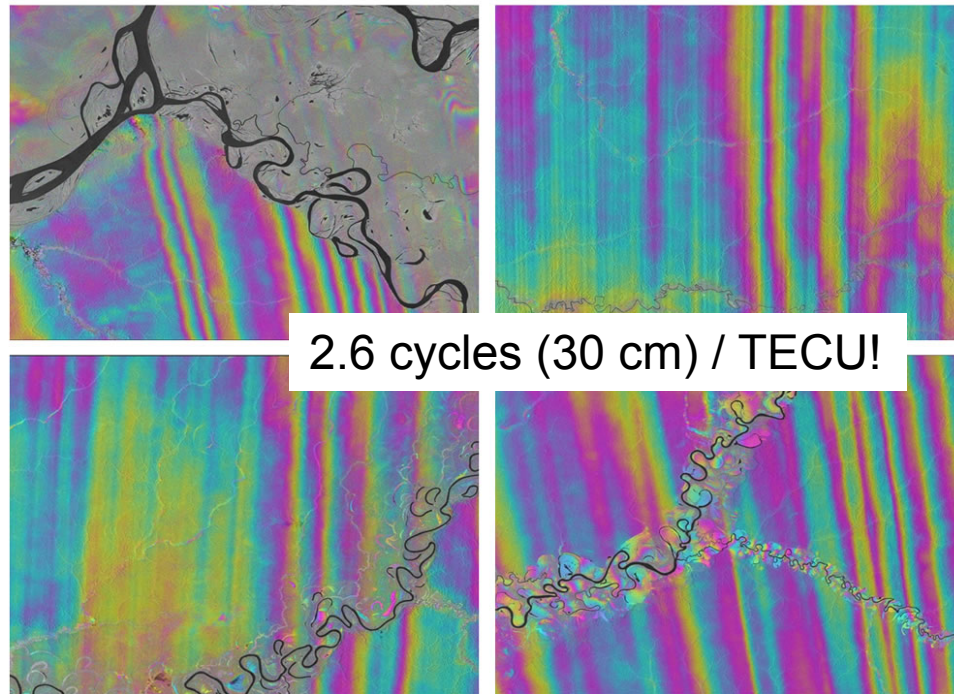
Atmospheric Phase (from ECMWF)



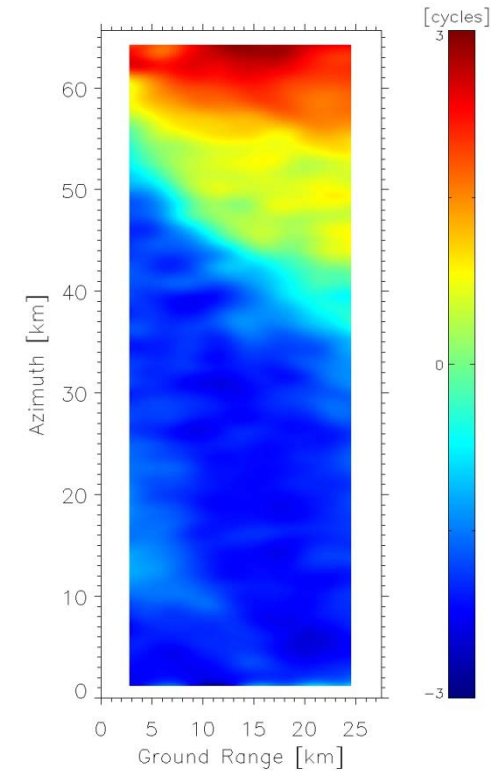
- ***Stromboli Volcano, Italy (926m)***
- **TerraSAR-X 2008-01-28/2008-08-02**
- **Baseline: 3.5 m**



Ionospheric Effects in L-Band



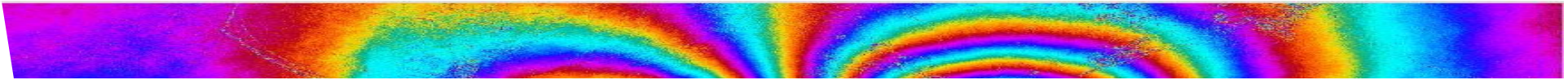
Ionospheric Signals in L-band InSAR Data near the Equator



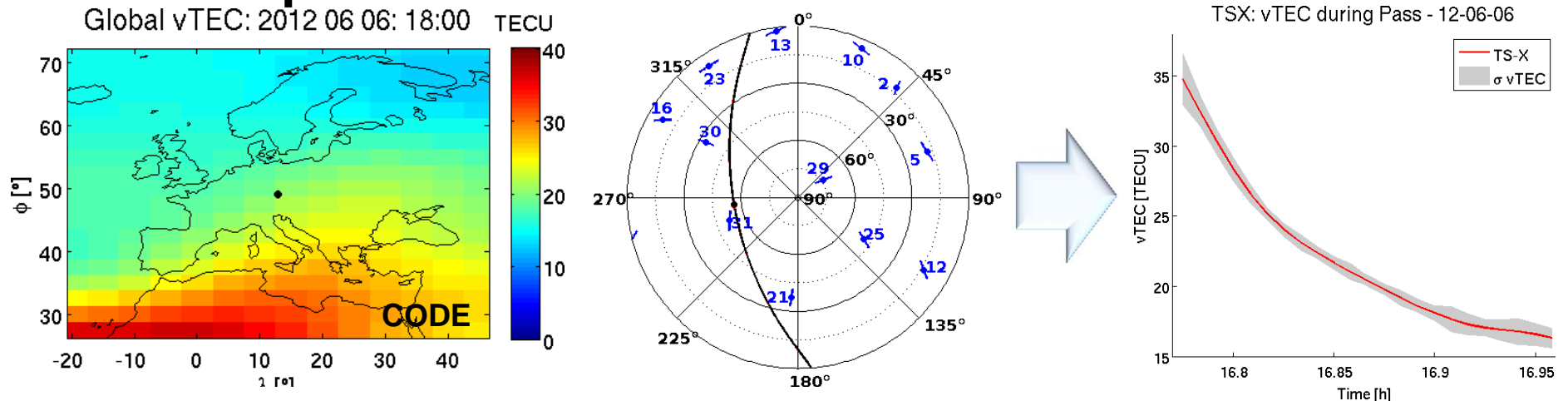
Countermeasures:

- Isolate dispersive ionosphere using split-bandwidth techniques
- Use available global TEC maps
- Use satellite GNSS measurements

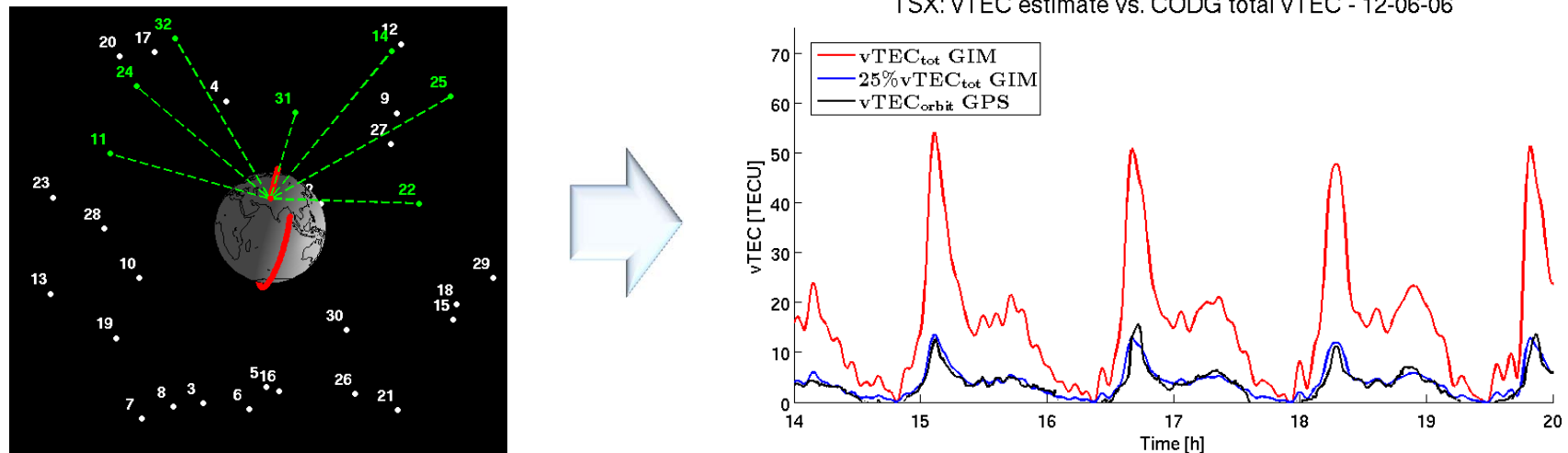




Ionospheric Correction: Global Models vs. Local GNS



In orbit: Satellite to satellite tracking

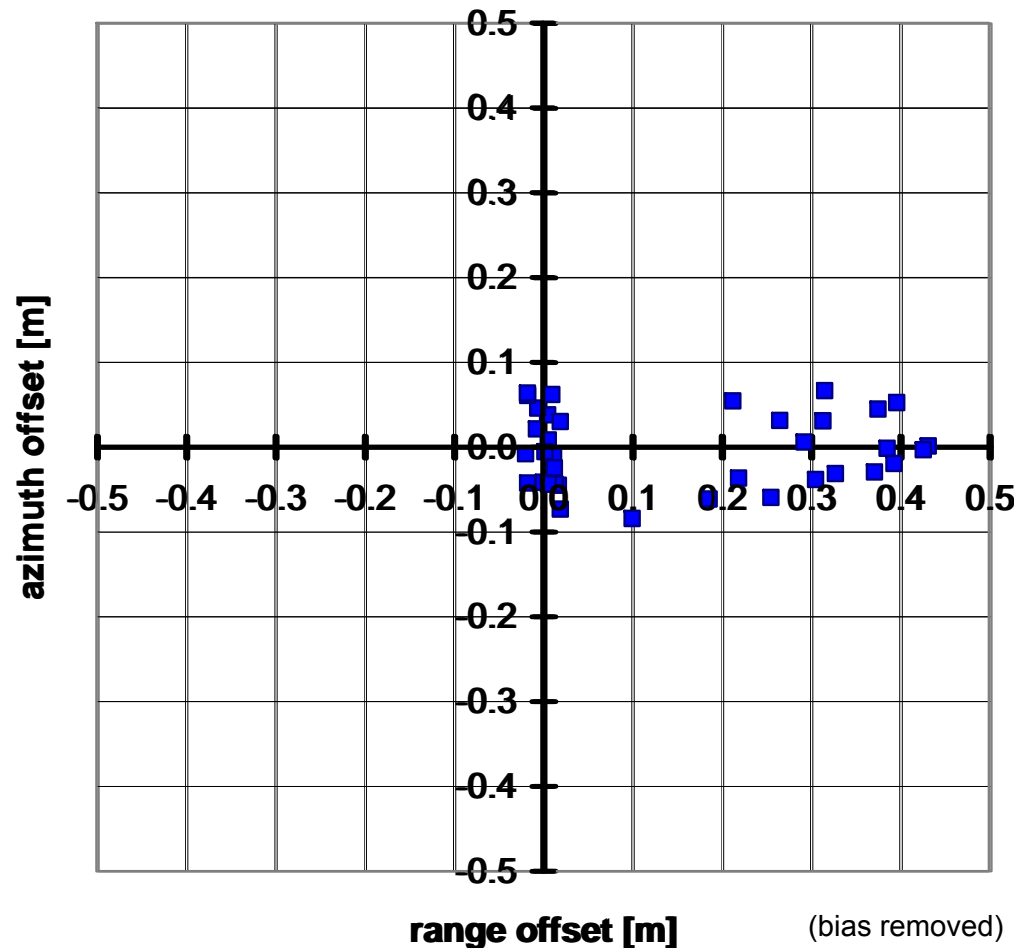


See: C. Gisinger, EGU 2013, Local ionospheric corrections derived from GNSS...



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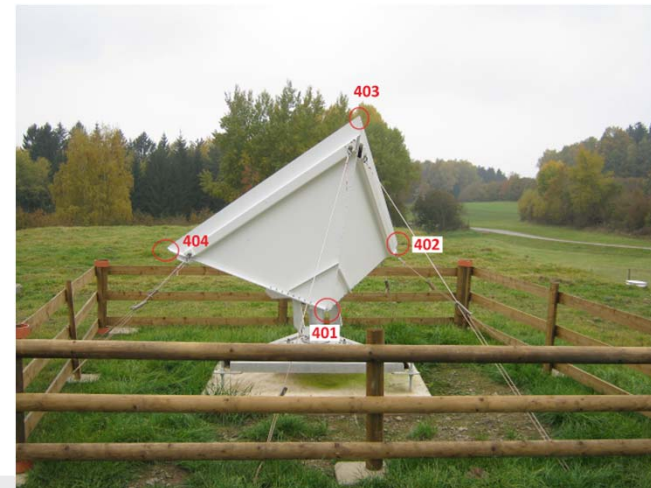
Atmospheric Correction - TSX Corner Reflector



Correction of
IERS 2010 Conventions (earth
tides, pole tides...,)
Tropospheric delay
Ionospheric delay
Continental drift

→ Azimut error $\sigma = 4.3$ cm

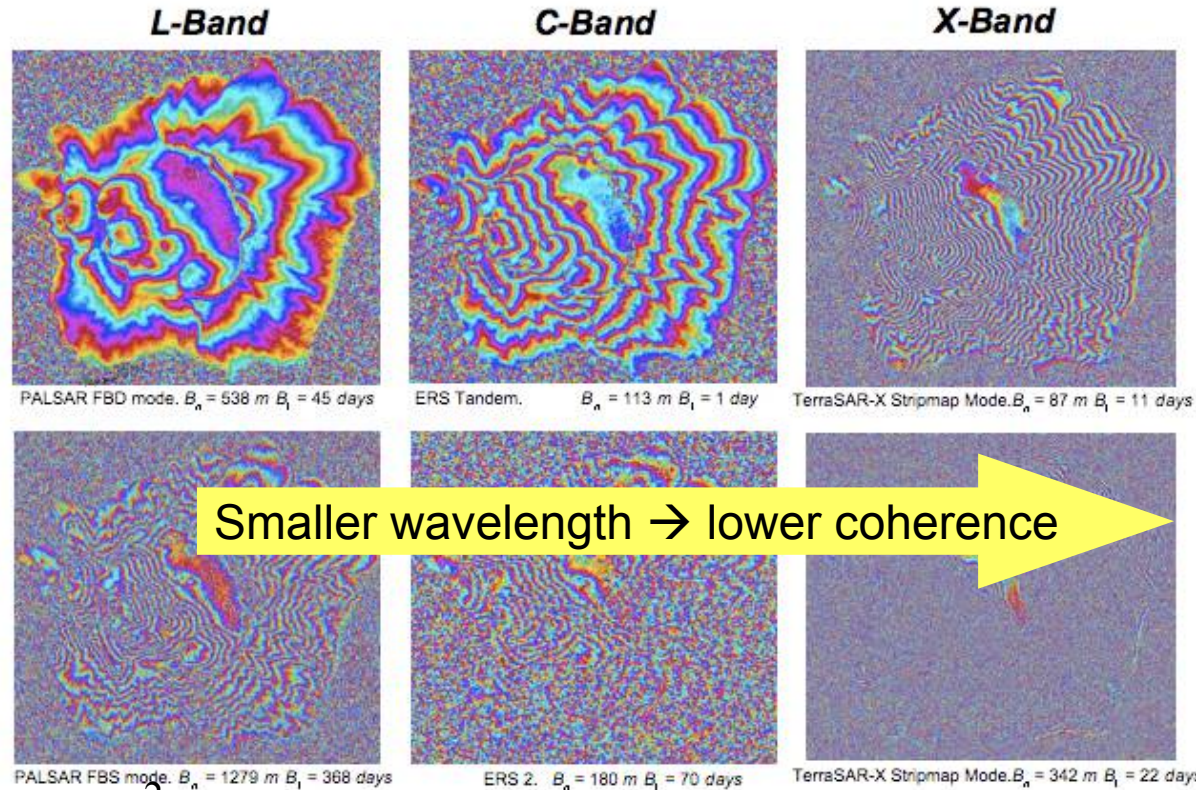
→ Range error $\sigma = 1.2$ cm



Enemy of Stacking: Temporal Decorrelation



Nisiros / Greece



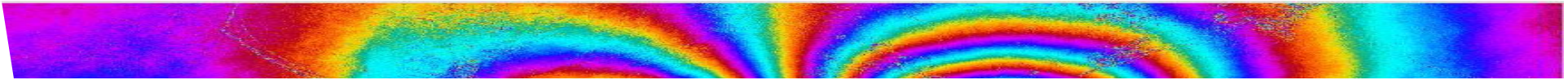
$$\gamma(t) = e^{-\frac{1}{2} \left(\frac{4\pi}{\lambda} \right)^2 \sigma_{drift}^2 t} \quad (\text{Zebker, 1992})$$

„time constant scales with square of λ “

$$\gamma(t) = (\gamma_0 - \gamma_k) e^{-\frac{t}{\tau}} + \gamma_k$$

Our current model





Coherence History in Indonesia (Java/Semarang)

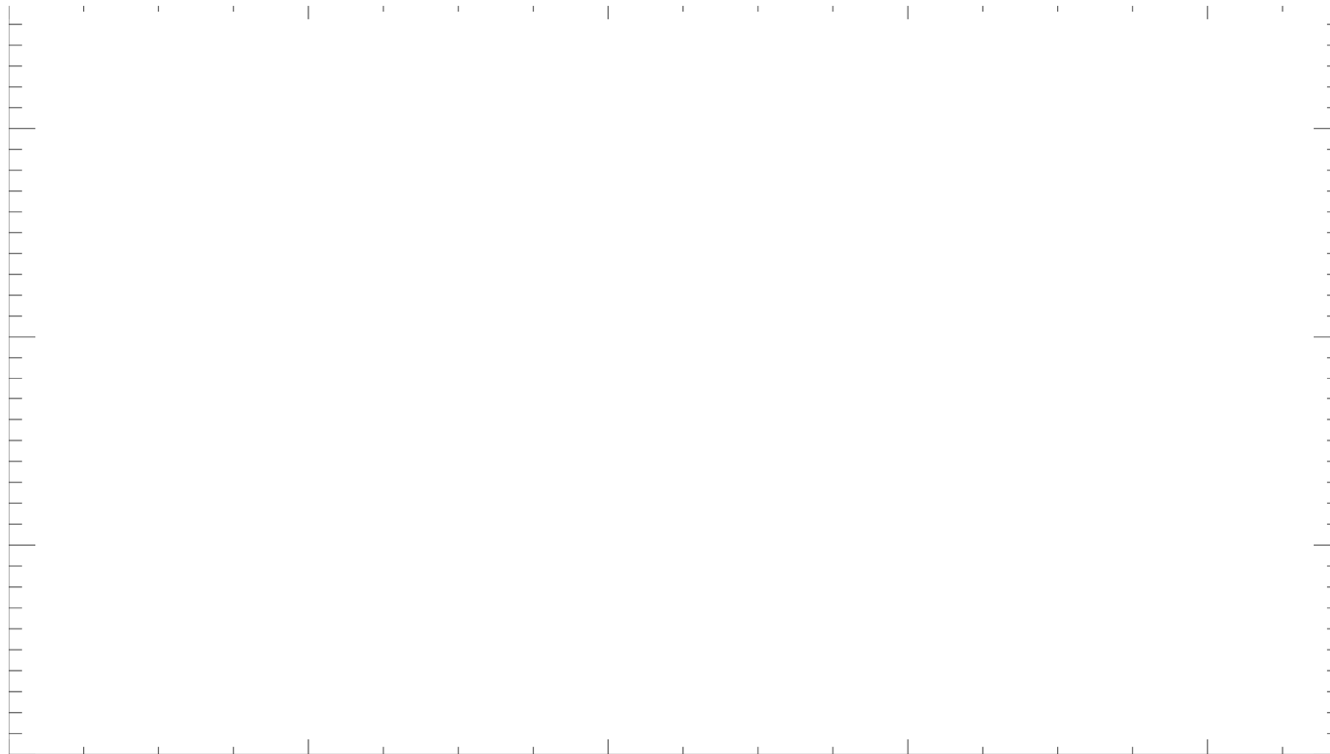
0, 46, 92, 138, ... 1472 Days (4 Years) Coherence Evolution (small baselines)





Coherence Evolution in Indonesia (Java/Semarang)

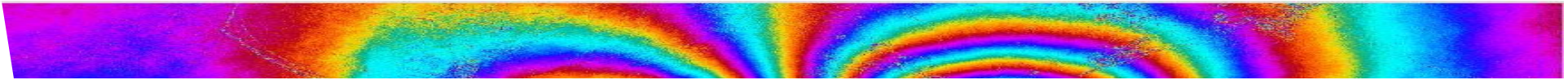
0, 46, 92, 138, ... 1472 Days (4 Years) Coherence Evolution
25 PALSAR scenes, small baselines only



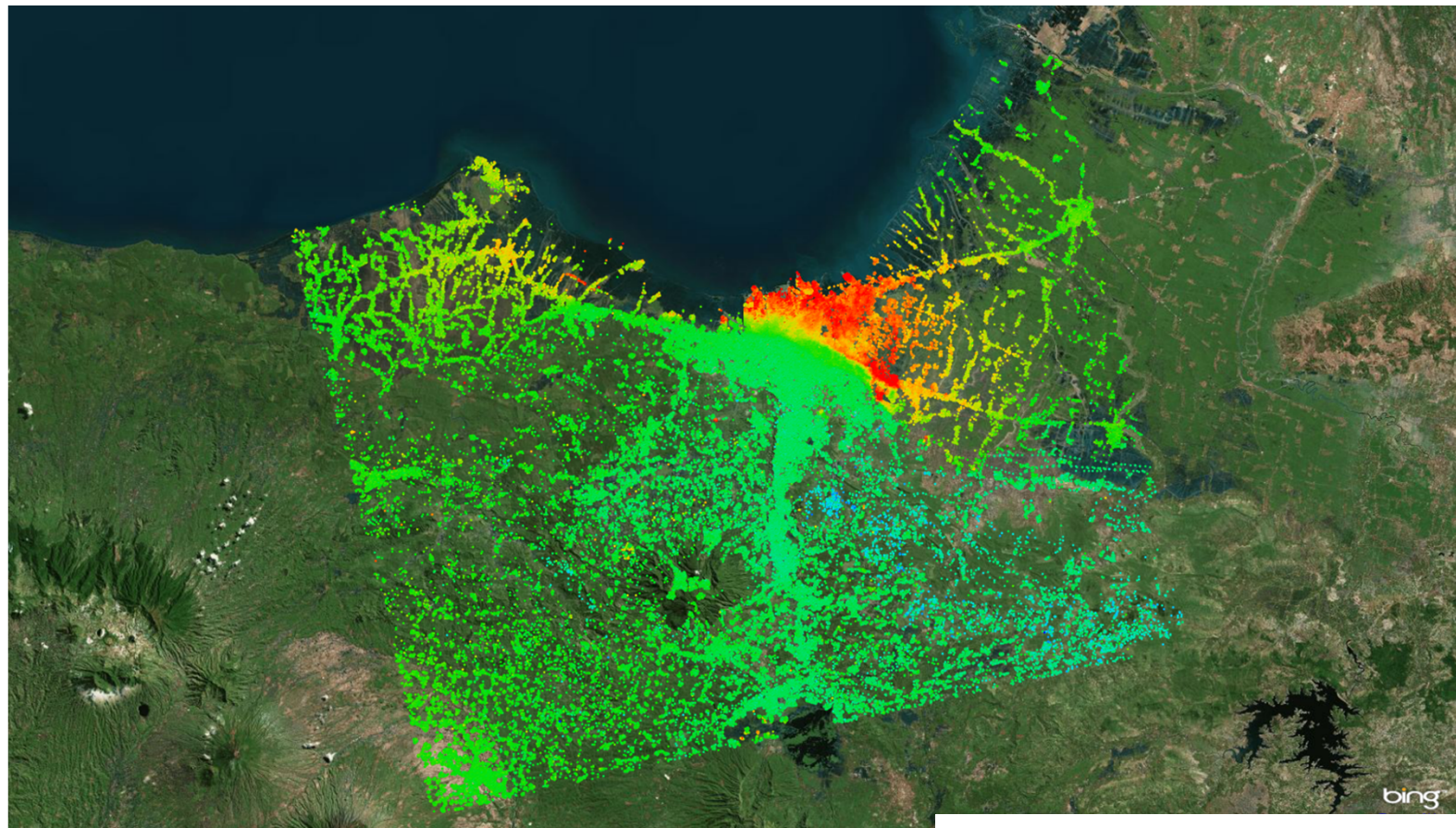
→ Optimal observation and processing strategies will be developed



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Semarang Persistent Scatterer Interferometry

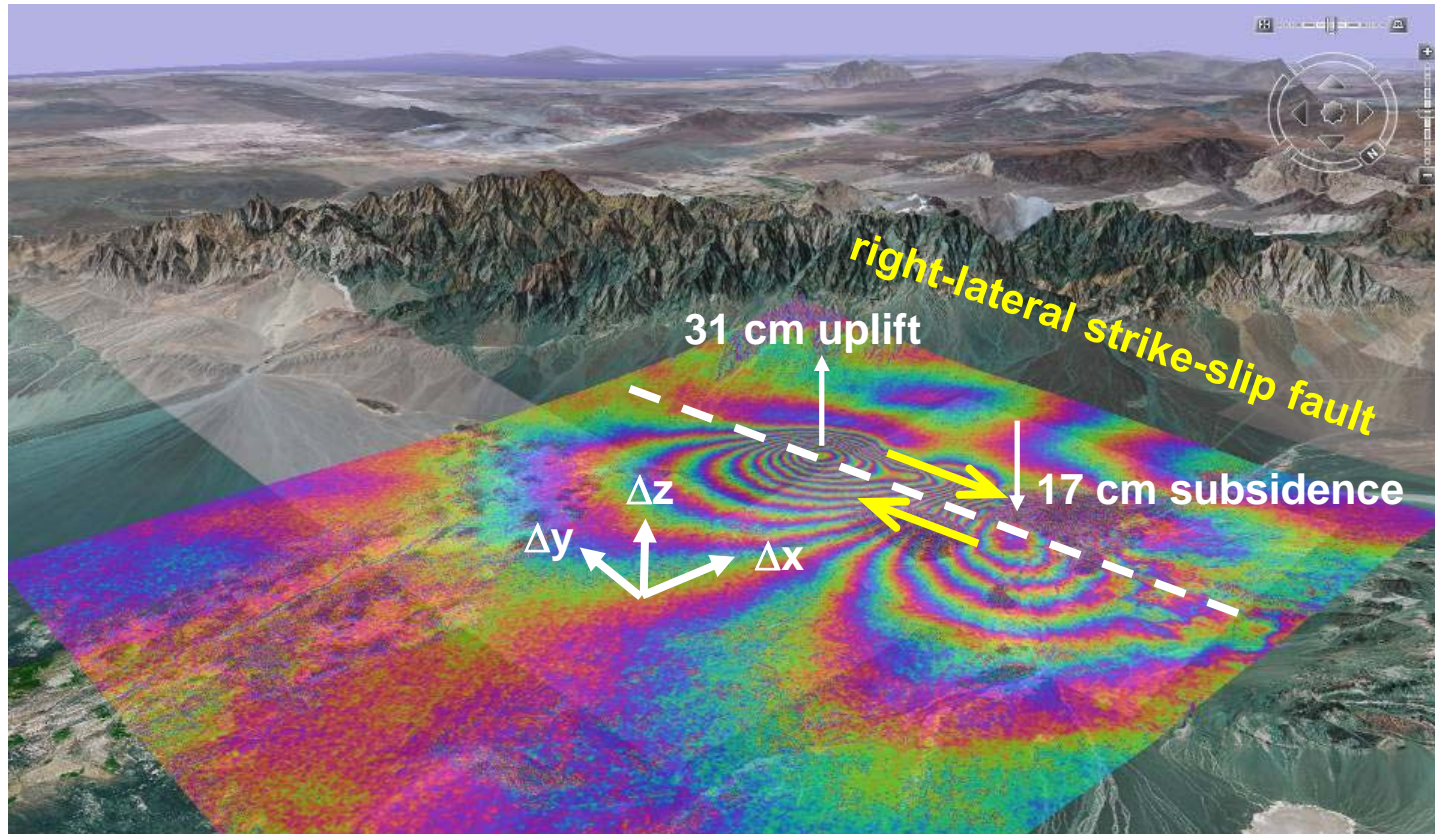


Fast motion, not measurable in X-Band!



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Challenge: 2/3-Dimensional Vector Wanted



Co-seismic Bam / Iran interferogram 26.12.2003 (ASAR)

→ > 2/3 Observations from different angles required



MAP-Estimator for 3D-Vector from n Observations

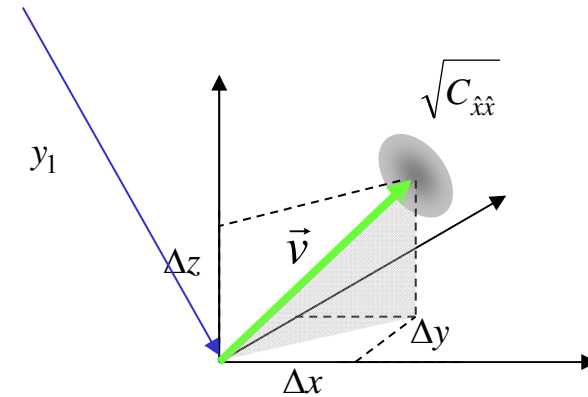
Model

$$\vec{y} = K\vec{v} = \begin{bmatrix} \sin \theta_1 \cos \alpha_1 & \sin \theta_1 \sin \alpha_1 & \cos \theta_1 \\ \dots & \dots & \dots \\ \dots & \dots & \dots \end{bmatrix} \begin{bmatrix} \Delta x \\ \Delta y \\ \Delta z \end{bmatrix}$$

$$\hat{x}_{MAP} = \left(K^T C_{\varepsilon\varepsilon}^{-1} K + C_{xx}^{-1} \right)^{-1} K^T C_{\varepsilon\varepsilon}^{-1} y$$

$$C_{\hat{x}\hat{x}} = \left(K^T C_{\varepsilon\varepsilon}^{-1} K \right)^{-1}$$

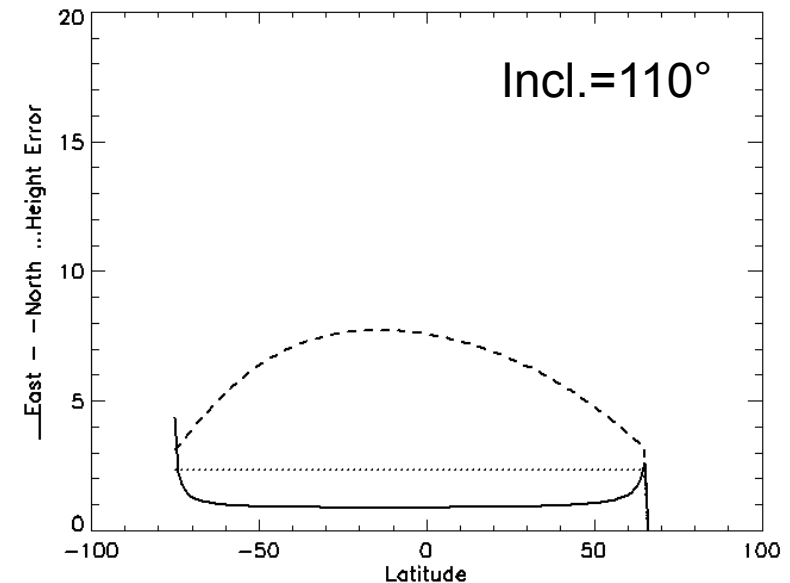
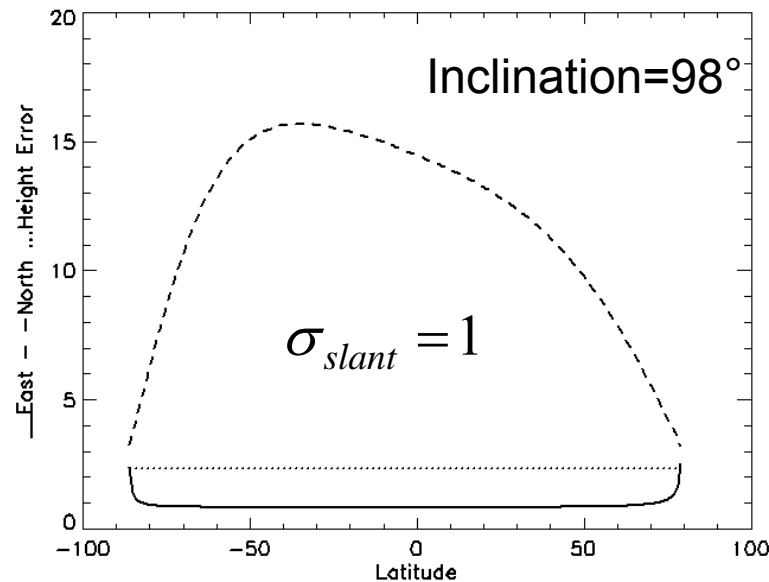
Covariance matrix of required 3D Vector estimate,
diagonal elements give accuracies in x, y, z (e.g. East, North, Height)





Bad 3D-Vector Conditioning with Polar Orbits

$\sigma_y=1$, (Asc, Desc) \times (30°, 45°)

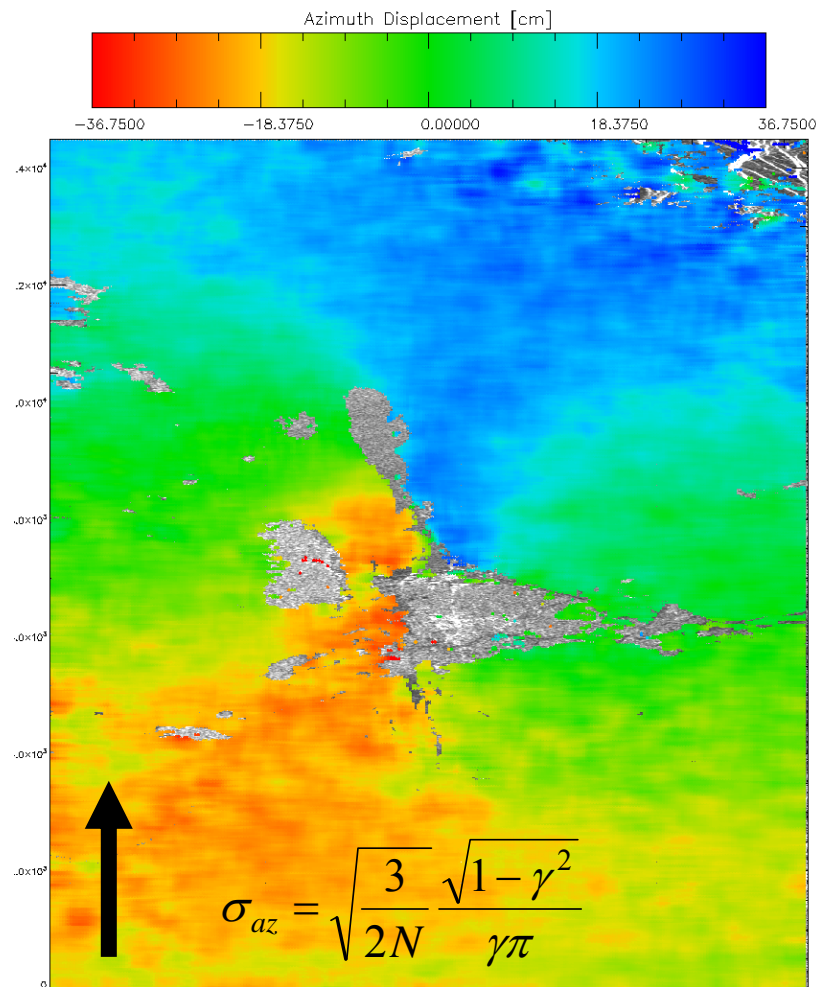


Possible improvements:

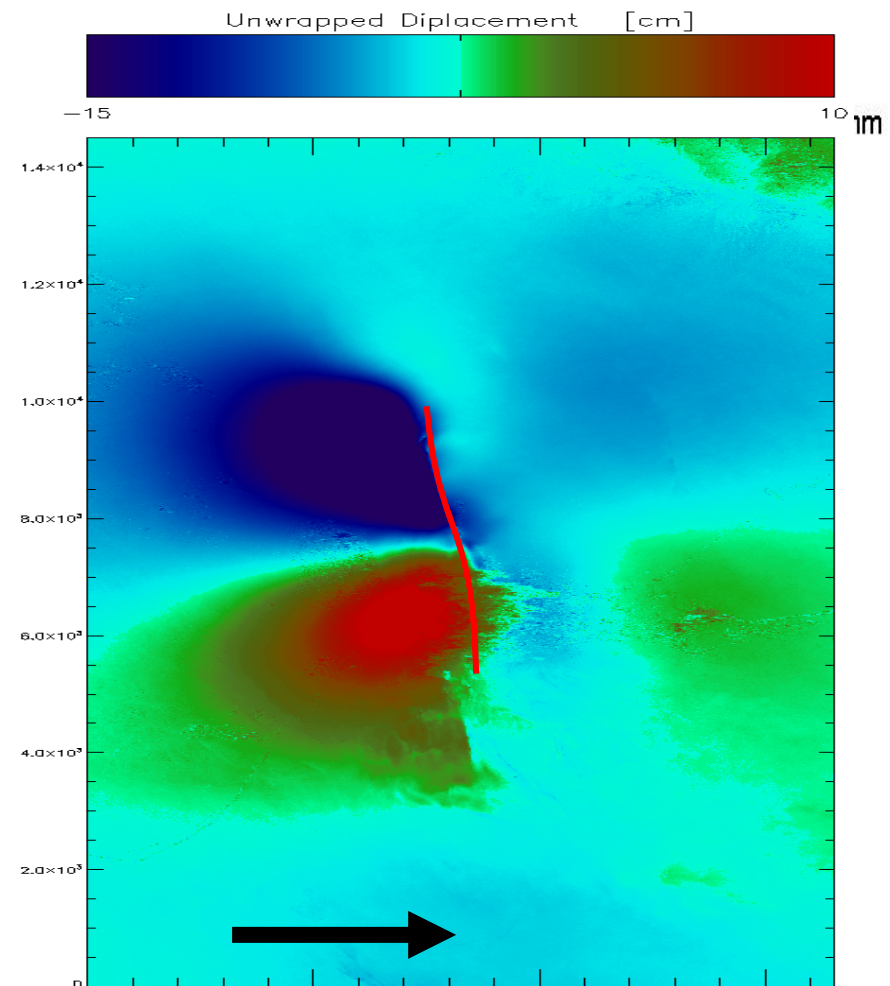
- non-polar orbit (other problems: power, ground stations, cryosphere)
- left and right look direction (requires maneuvers & special satellite design)
- use second satellite
- speckle tracking to support azimuth component ...



Earthquake Shifts from InSAR & Speckle Tracking



Azimuth (correlation)



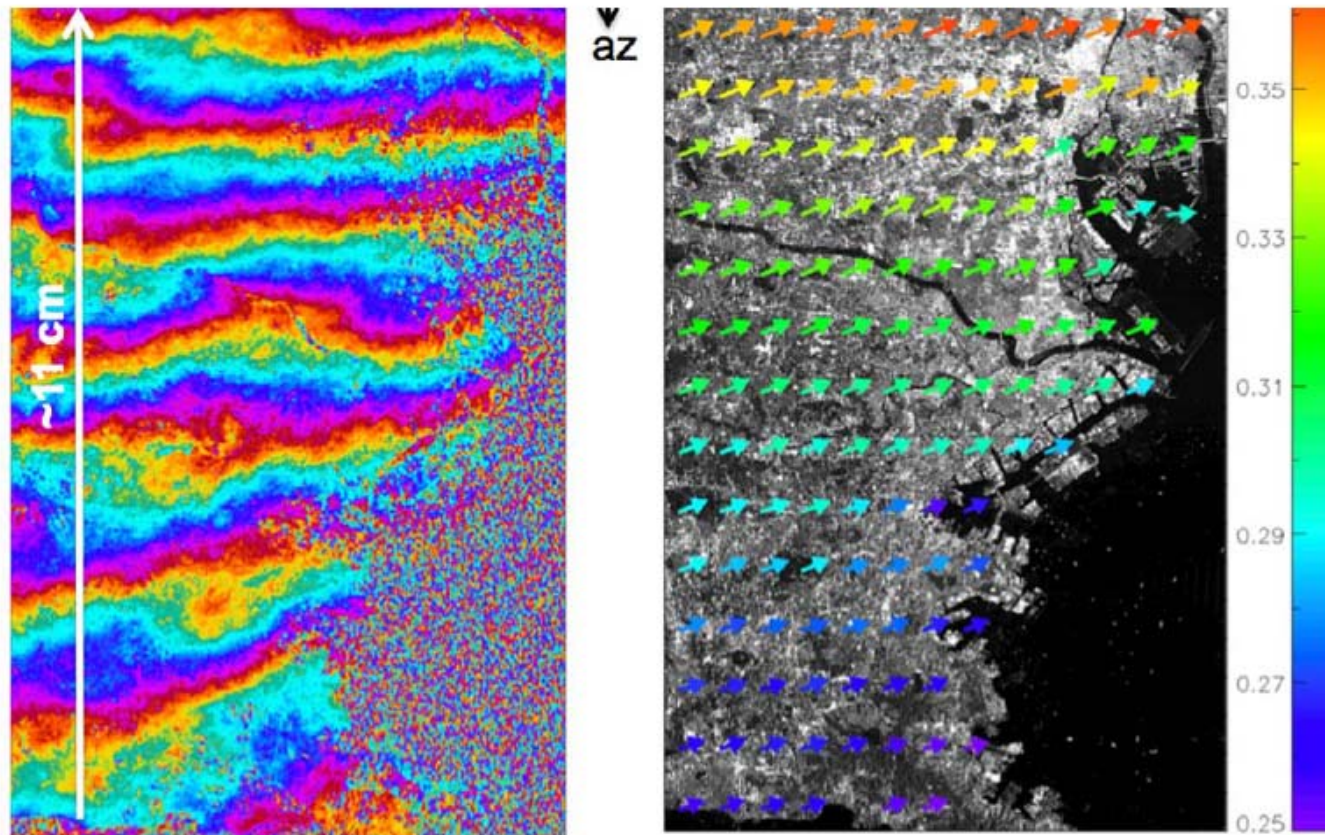
Range (interferometry)

Bam / Iran 26.12.2003 (ASAR)



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Ground Displacement from Speckle Tracking / Radargrammetry



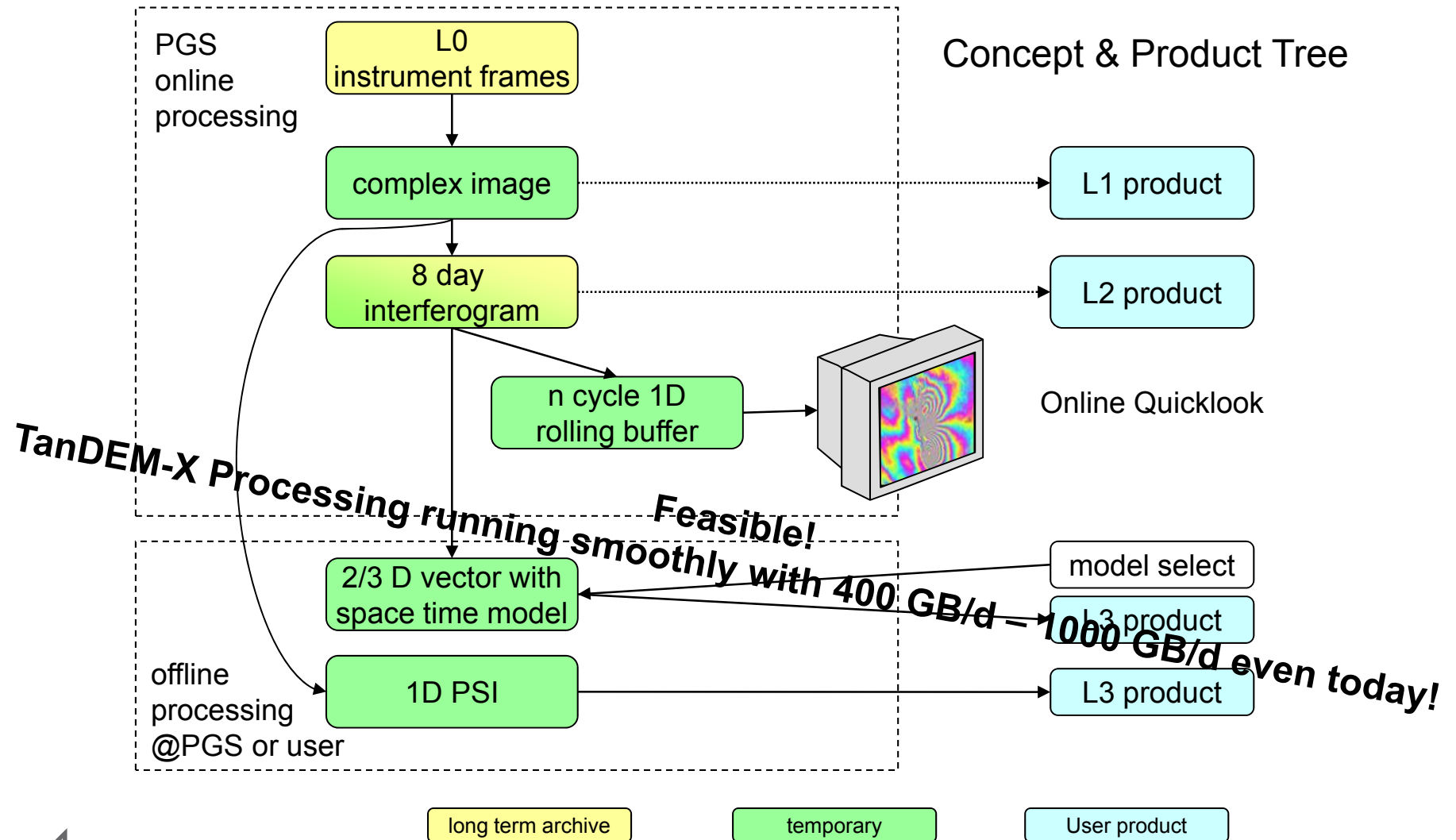
GRSL 2012: Ground Displacement Measurement by TerraSAR-X
Image Correlation: The 2011 Tohoku-Oki Earthquake

Nestor Yague-Martinez, Michael Eineder, *Member, IEEE*, Xiao Ying Cong, and Christian Minet



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Processing Challenge: 3-4 TB/day



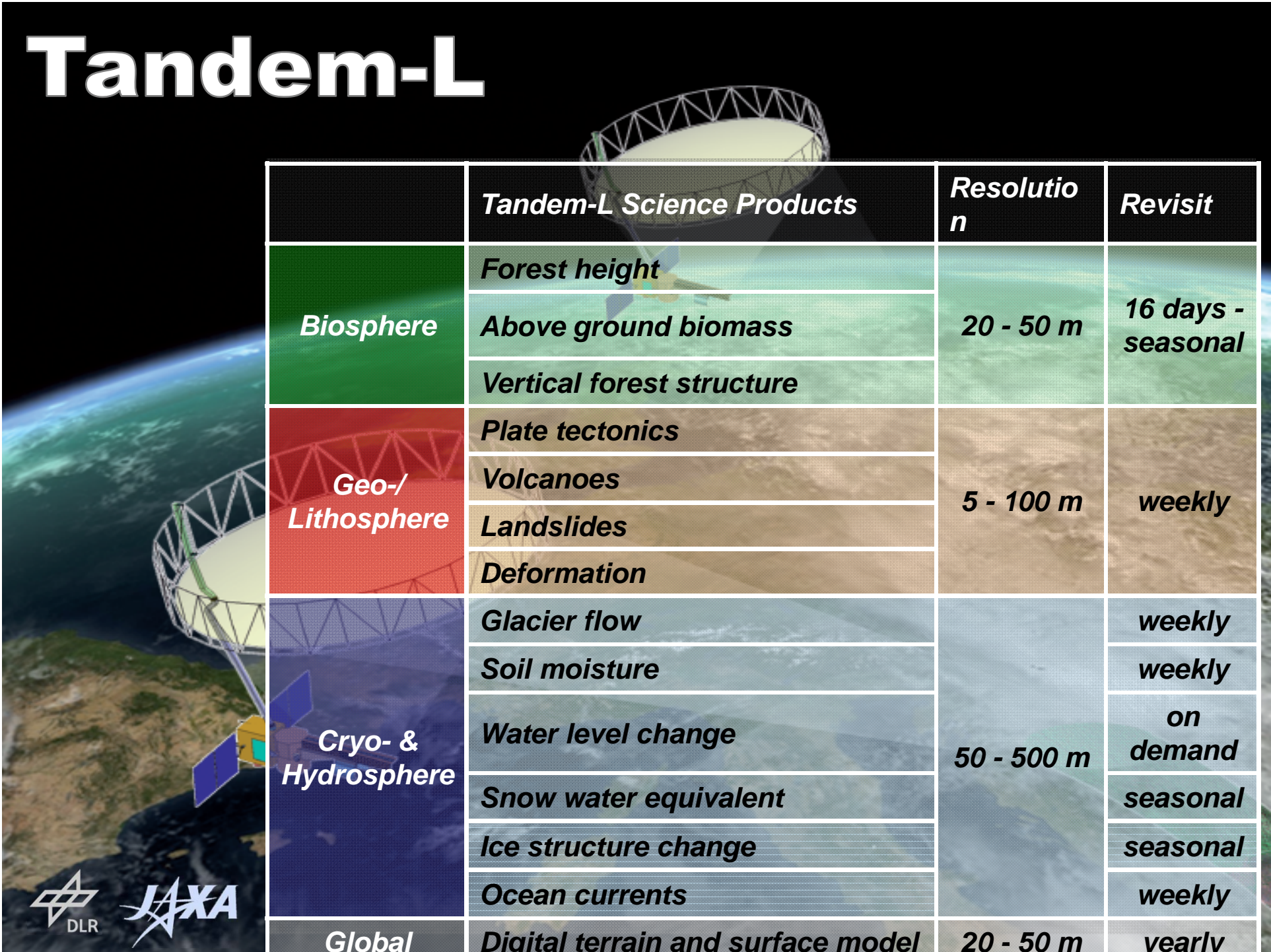


Conclusions

- Challenges are
 - accuracy over large areas
 - ionospheric and tropospheric correction required
 - 2/3D-vector
 - ascending + descending orbits
 - (inclusion of geophysical models)
 - Decorrelation
 - L-band promising
- **Exciting mission - challenges can be met**



Tandem-L



	<i>Tandem-L Science Products</i>	<i>Resolution</i>	<i>Revisit</i>
Biosphere	<i>Forest height</i>	<i>20 - 50 m</i>	<i>16 days - seasonal</i>
	<i>Above ground biomass</i>		
	<i>Vertical forest structure</i>		
Geo-/ Lithosphere	<i>Plate tectonics</i>	<i>5 - 100 m</i>	<i>weekly</i>
	<i>Volcanoes</i>		
	<i>Landslides</i>		
	<i>Deformation</i>		
Cryo- & Hydrosphere	<i>Glacier flow</i>	<i>50 - 500 m</i>	<i>weekly</i>
	<i>Soil moisture</i>		<i>weekly</i>
	<i>Water level change</i>		<i>on demand</i>
	<i>Snow water equivalent</i>		<i>seasonal</i>
	<i>Ice structure change</i>		<i>seasonal</i>
	<i>Ocean currents</i>		<i>weekly</i>
Global	<i>Digital terrain and surface model</i>	<i>20 - 50 m</i>	<i>yearly</i>

